# NOIDA INSTITUTE OF ENGINEERING & TECHNOLOGY, GREATER NOIDA, GAUTAM BUDDH NAGAR (AN AUTONOMOUS INSTITUTE)



# Affiliated to

# DR. A.P.J. ABDUL KALAM TECHNICAL UNIVERSITY, LUCKNOW



**Evaluation Scheme & Syllabus**For

**Electronics and Communication & Engineering** 

**Third Year** 

(Effective from the Session: 2025-26)

# NOIDA INSTITUTE OF ENGINEERING & TECHNOLOGY, GREATER NOIDA, GAUTAM BUDDH NAGAR (AN AUTONOMOUS INSTITUTE)

# **Bachelor of Technology**

# **Electronics and Communication Engineering**

# **Evaluation Scheme**

# SEMESTER-V

Sl.	Subject	Subject	Types of	Periods Evaluation Schemes			En Seme		Total	Credit				
No.	Codes	Subject	Subjects		Т	P	CT	TA	TOTAL	PS	TE	PE		
1	BEC0501	Electromagnetic Field Theory and Antenna	Mandatory	3	1	0	30	20	50		100		150	4
2		Departmental Elective-I	Departmental Elective	3	0	0	30	20	50		100		150	3
3		Departmental Elective-II	Departmental Elective	3	0	0	30	20	50		100		150	3
4	BCSCC0501	Design Thinking –II	Mandatory	2	1	0	30	20	50		100		150	3
5	BEC0551	Wireless Communication	Mandatory	0	0	6				50		100	150	3
6	BEC0552	Computer Networks	Mandatory	0	0	6				50		100	150	3
7		Department of Elective Lab	Departmental Elective	0	0	4				50		50	100	2
8	BEC0559	Internship Assessment	Mandatory	0	0	2				50			50	1
9	BNC0502/ BNC0501	Essence of Indian Traditional Knowledge/ Constitution of India	Compulsory Audit	2	0	0	30	20	50		50			NA
10		MOOCs (Essential for Hons. Degree)												
		TOTAL		13	2	18	120	80	200	200	400	250	1050	22

#### \* List of MOOCs Based Recommended Courses for Third year (Semester-V) B. Tech Students

Sr. No.	Subject Code	Course Name	University / Industry Partner Name	No of Hours	Credits
1	BMC0070	C on Linux	Infosys Wingspan (Infosys Springboard)	10h 20m	0.5
2	BMC0104	Wireless Evolution and 4G LTE Overview	Infosys Wingspan (Infosys Springboard)	52h 4m	4

#### **PLEASE NOTE: -**

- A 3-4 weeks Internship shall be conducted during summer break after semester-IV and will be assessed during semester-V
- Compulsory Audit (CA) Courses (Non-Credit BNC0502/BNC0501)
  - All Compulsory Audit Courses (a qualifying exam) do not require any credit.
  - The total and obtained marks are not added in the grand total.

#### **Abbreviation Used:**

L: Lecture, T: Tutorial, P: Practical, CT: Class Test, TA: Teacher Assessment, PS: Practical Sessional, TE: Theory End Semester Exam., CE: Core Elective, OE: Open Elective, DE: Departmental Elective, PE: Practical End Semester Exam, CA: Compulsory Audit, MOOCs: Massive Open Online Courses.

# **List of Departmental Electives**

Sr. No.	<b>Subject Codes</b>	Subject Name	<b>Departmental Electives</b>	Bucket Name
1	BEC0511	Embedded System Design	Departmental Elective-I	
2	BEC0513	Introduction to Robotics and it's Applications	Departmental Elective-II	Embedded & Robotics
3	BEC0511 P	Embedded System Design Lab	Departmental Elective	
4	BEC0512	Machine Learning	Departmental Elective-I	
5	BEC0514	Artificial Intelligence	Departmental Elective-II	Artificial Intelligence
6	BEC0512 P	AI & ML Lab	Departmental Elective	
7	BEC0511	Embedded System Design	Departmental Elective-I	
8	BEC0515	VLSI Technology	Departmental Elective-II	Embedded and VLSI
9	BEC0511 P	Embedded System Design Lab	Departmental Elective	

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# **Bachelor of Technology**

# **Electronics and Communication Engineering**

# **Evaluation Scheme**

			SEM	<b>IEST</b>	ER-	VI	
Sl.	Subject	Subject	Types of	P	erio	ds	
No.	Codes	· ·	Subjects	-	TT.	1	7

Sl.	Subject		Т	D.	erio	le.	Fx	zalnati	on Scheme	oc .	En	d		
	•	Subject	Types of Subjects	1	L'unution schemes		Seme	ster	Total	Credit				
No.	Codes	_	Subjects	L	T	P	CT	TA	TOTAL	PS	TE	PE		
1	BEC0601	5G Technology	Mandatory	3	1	0	30	20	50		100		150	4
2		Departmental Elective-III	Departmental Elective	3	0	0	30	20	50		100		150	3
3		Departmental Elective-IV	Departmental Elective	3	0	0	30	20	50		100		150	3
4		Open Elective-I	Open Elective	3	0	0	30	20	50		100		150	3
5	BEC0651	IoT Architecture and Protocols	Mandatory	0	0	6				50		100	150	3
6	BEC0652	Digital Signal Processing	Mandatory	0	0	6				50		100	150	3
7		Departmental Elective Lab	Departmental Elective	0	0	2				25		25	50	1
8	BEC0659	Minor Project	Mandatory	0	0	6				50		100	150	3
9	BNC0601/ BNC0602	Constitution of India / Essence of Indian Traditional Knowledge	Compulsory Audit	2	0	0	30	20	50		50			
		MOOCs	MOOCs			_								
		(Essential for Hons. Degree)												
		TOTAL		14	1	20	120	80	200	175	400	325	1100	23

#### \* List of MOOCs Based Recommended Courses for Third year (Semester-VI) B. Tech Students

Sr. No.	Subject Code	Course Name	University / Industry Partner Name	No of Hours	Credits
1	BMC0076	Data Structures and Algorithms	Infosys Wingspan (Infosys Springboard)	18h 5m	1
2	BMC0082	Introduction to AI & ML	Infosys Wingspan (Infosys Springboard)	64h 13m	4
3	BMC0103	Wireless 5G Overview	Infosys Wingspan (Infosys Springboard)	55h 44m	4

#### **PLEASE NOTE: -**

- A 3-4 weeks Internship shall be conducted during summer break after semester-VI and will be assessed during Semester-VII
- Compulsory Audit (CA) Courses (Non-Credit BNC0601/BNC0602)
  - All Compulsory Audit Courses (a qualifying exam) do not require any credit.
  - > The Total and obtained marks are not added in the Grand Total.

#### **Abbreviation Used:**

L: Lecture, T: Tutorial, P: Practical, CT: Class Test, TA: Teacher Assessment, PS: Practical Sessional, TE: Theory End Semester Exam., CE: Core Elective, OE: Open Elective, DE: Departmental Elective, PE: Practical End Semester Exam, CA: Compulsory Audit, MOOCs: Massive Open Online Courses.

# **List of Departmental Electives**

Sr. No.	Subject Codes	Subject Name	<b>Departmental Electives</b>	Bucket Name
1	BEC0611	Control System and Automation	Departmental Elective-I	
2	BEC0614	Robotics Design Mechanism	Departmental Elective-II	Embedded & Robotics
3	BEC0614P	Robotics Lab	Departmental Elective	
4	BEC0612	Image Processing and Pattern Recognition	Departmental Elective-I	
5	BEC0615	ANN & Deep Learning	Departmental Elective-II	Artificial Intelligence
6	BEC0612P	Image Processing and Pattern Recognition Lab	Departmental Elective	
7	BEC0613	VLSI Testing and Reliability	Departmental Elective-I	
8	BEC0616	Real Time Operating System	Departmental Elective-II	Embedded and VLSI
9	BEC0616P	Real Time Operating System Lab	Departmental Elective	

# NOIDA INSTITUTE OF ENGINEERING & TECHNOLOGY, GREATER NOIDA, GAUTAM BUDDH NAGAR (AN AUTONOMOUS INSTITUTE)

A student will be eligible to get Under Graduate degree with Honours only, if he/she completes the additional MOOCs courses such as Coursera certifications, or any other online courses recommended by the Institute (Equivalent to 20 credits). During Complete B.Tech. Program Guidelines for credit calculations are as follows.

- 1. For 6 to 12 Hours =0.5 Credit
- 2. For 13 to 18 = 1 Credit
- 3. For 19 to 24 = 1.5 Credit
- 4. For 25 to 30 = 2 Credit
- 5. For 31 to 35 = 2.5 Credit
- 6. For 36 to 41 = 3 Credit
- 7. For 42 to 47 = 3.5 Credit
- 8. For 48 and above =4 Credit

For registration to MOOCs Courses, the students shall follow Coursera registration details as per the assigned login and password by the Institute these courses may be cleared during the B. Tech degree program (as per the list provided). After successful completion of these MOOCs courses, the students shall provide their successful completion status/certificates to the Controller of Examination (COE) of the Institute through their coordinators/Mentors only. The students shall be awarded Honours Degree as per following criterion.

- i. If he / she secures 7.50 as above CGPA.
- ii. Passed each subject of that degree program in the single attempt without any grace.
- iii. Successful completion of MOOCs based 20 credits

	Bachelor of Technology Third Year		
<b>Course Code</b>	BEC0501	LTP	Credits
<b>Course Title</b>	Electromagnetic Field Theory and Antenna	310	4
<b>Course Objective</b>	es: The student will learn about		•
static electric and mediums, students energy flow in elec	magnetic field theory, starting with an exploration of various coordinate systems and the application of vector magnetic fields. By delving into Maxwell's equations for time-varying fields and examining wave partial will gain insights into the fundamental principles governing electromagnetic phenomena. Pointing's the tromagnetic radiation, while exploration of basic antenna properties will provide a foundation for understated populations in modern communication systems.	propagati eorem wi	on in differen ll elucidate the
Pre- requisites: B	asic Vector Algebra		
	Course Contents / Syllabus		
UNIT-I	Coordinate Systems and Transformation		8 hours
	formation: Cartesian, Cylindrical and Spherical. Vector calculus: Differential length, area and volume, le rator, Gradient, Divergence of a vector, Divergence theorem, Curl of a vector, Stokes's theorem, Laplacia		
UNIT-II	Electrostatic fields and Magnetostatic fields		8 hours
relaxation time, l Magnetic boundar	<b>√</b>		ector potential
UNIT-III	Electromagnetic waves		8 hours
	ons in final form, plane wave propagation in different medium: lossy dielectrics, lossless dielectrics polarization, Poynting's theorem, radiation from small current element, power density and radiation resigned dipole.		
UNIT-IV			
UNII-IV	Antenna fundamental		8 hours
Introduction, Basi	Antenna fundamental ic antenna parameters, Patterns, Beam area, Radiation intensity, Beam efficiency, Directivity and Gain, Diss, Effective height, The radio communication link.	irectivity	
Introduction, Basi	ic antenna parameters, Patterns, Beam area, Radiation intensity, Beam efficiency, Directivity and Gain, Di	irectivity	
Introduction, Basi Antenna apertures UNIT-V	ic antenna parameters, Patterns, Beam area, Radiation intensity, Beam efficiency, Directivity and Gain, Diss, Effective height, The radio communication link.		and resolution  8 hours
Introduction, Basis Antenna apertures UNIT-V  The Loop Antenn Design of Micros	c antenna parameters, Patterns, Beam area, Radiation intensity, Beam efficiency, Directivity and Gain, Diss, Effective height, The radio communication link.  Practical Antennas  a, Design and its Characteristic, Application of Loop Antennas. Horn Antennas, Helical Antennas, The		and resolution  8 hours  odic Antenna,  Bloom's
Introduction, Basis Antenna apertures UNIT-V  The Loop Antenn Design of Micros	c antenna parameters, Patterns, Beam area, Radiation intensity, Beam efficiency, Directivity and Gain, Diss, Effective height, The radio communication link.  Practical Antennas  a, Design and its Characteristic, Application of Loop Antennas. Horn Antennas, Helical Antennas, The trip Antenna, Parabolic Reflector Antennas, Feed Methods for Parabolic Reflectors.		and resolution  8 hours  odic Antenna,

CO 1	Apply different coordinate systems and vector calculus to solve problems of electromagnetic fields	K3, K4					
CO 2	Explain and apply the concepts of static Electric and Magnetic fields.	K2, K3					
CO 3	Explain Maxwell's equations and their applications.	K2, K3					
CO 4	Explain and calculate the fundamental properties of Antenna K2, K4						
CO 5	Analyze practical Antennas with applications. K2, K3						
Text books:							
1. MN	IO Sadiku, "Elements of Electromagnetics', Oxford University Press, 2014.						
2. Joh	2. John D Kraus, Ronald J Marhefka and Ahmad S. Khan, "Antennas and Wave Propagation", Fourth Edition, Tata McGraw Hill, 2011.						
3. C. A	A. Balanis, "Antenna Theory Analysis and Design", John Wiley, 2016.						
Reference Bo	oks:						
1. W	1. W H Hayt and JA Buck, "Engineering Electromagnetics", McGraw- Hill Education, 2013.						
	R. Harish, M. Sachidananda, "Antennas and Wave Propagation", Oxford University Press, 2007.						
3. R. I	. Yadava, Electromagnetic Waves, Khanna Publishing House, Delhi, 2018.						
4. A. I	Das, Sisir K. Das, "Microwave Engineering", Tata McGraw Hill, 2001.						
NPTEL/ You	Tube/ Faculty Video Link:						
Unit I	https://www.youtube.com/watch?v=3qd1JT7sRG8						
Unit II	II https://www.youtube.com/watch?v=F5KFYBdjzuE&list=PLVFqK_9GOGXnV8fwd2YmU						
Unit III	Jnit III https://www.youtube.com/watch?v=7NZhmOIyYQM						
Unit IV	https://www.youtube.com/watch?v=h51mFbIgZRI&list=PLbRMhDVUMngfytbQXzasPM						
Unit V	https://www.youtube.com/watch?v=wx_tIvaajAI&list=PL3UZlxOnyu9CRoBFsG5x-VqYeC69FmMZT						

Bachelor of Technology Third Year						
Course Code	BEC0503	LTP	Credits			
Course Title	Design Thinking -II	210	3			
a a						

**Course Objectives: The student will learn about** 

The Design Thinking skills by learning & applying advanced and contextual Design Thinking Tools. It aims to solve a Real-Life Problem by applying Design Thinking to create an impact for all the stakeholders.

**Pre-requisites:** Student must complete Design Thinking-I course

# **Course Contents / Syllabus**

UNIT-I Introduction 8 hours

Design thinking & Innovation, Design Thinking Mindset and Principles, recap of 5-Step Process of Design Thinking, Design Approaches, additional in-depth examples of each design approaches. Simon Sinek's – Start with Why, The Golden Circle, Asking the "Why" behind each example (an inclass activity of asking 5-WHYS), The Higher Purpose, in-class activity for LDO & sharing insight.

Visualization and its importance in design thinking, reflections on wheel of life (*in-class activity for visualization & Wheel of Life*), Linking it with Balancing Priorities (*in class activity*), DBS Singapore and Bank of Americas' Keep the Change Campaign. Litter of Light & Arvind Eye Care Examples, understanding practical application of design thinking tools and concepts, case study on McDonald's Milkshake / Amazon India's Rural Ecommerce & Gillette.

Working on 1-hour Design problem, Applying RCA and Brainstorm on innovative solutions. Main project allocation and expectations from the project

### UNIT-II Refinement and Prototyping

8 hours

Refine and narrow down to the best idea, 10-100-1000gm, QBL, Design Tools for Convergence – SWOT Analysis for 1000gm discussion. *Inclass activity for 10-100-1000gm & QBL*.

Prototyping (Convergence): Prototyping mindset, tools for prototyping – Sketching, paper models, pseudo-codes, physical mockups, Interaction flows, storyboards, acting/role-playing etc, importance of garnering user feedback for revisiting Brainstormed ideas, Napkin Pitch, Usability, Minimum Viable Prototype, Connecting Prototype with 3 Laws, A/B Testing, Learning Launch. Decision Making Tools and Approaches – Vroom Yetton Matrix, Shift-Left, Up, Right, Value Proposition, Case study: Career buddy, You-Me-Health Story & IBM Learning Launch.

In-class activities on prototyping- paper-pen / physical prototype/ digital prototype of project's 1000gm idea

# UNIT-III Storytelling, Testing and Assessment

8 hours

Storytelling: Elements of storytelling, Mapping personas with storytelling, Art of influencing, Elevator Pitch, Successful Campaigns of well-known examples, *in-class activity on storytelling*.

Testing of design with people, conducting usability test, testing as hypothesis, testing as empathy, observation and shadowing methods, Guerrilla Interviews, validation workshops, user feedback, record results, enhance, retest, and refine design, Software validation tools, design parameters, alpha & beta testing, Taguchi, defect classification, random sampling.

Final Project Presentation and assessing the impact of using design thinking

# UNIT-IV Innovation, Quality and Leadership

8 hours

Innovation: Need & Importance, Principles of innovations, Asking the Right Questions for innovation, Rationale for innovation, Quality: Principles & Philosophies, Customer perception on quality, Kaizen, 6 Sigma. FinTech case study of Design Thinking application — CANVAS Leadership, types, qualities and traits of leaders and leadership styles, Leaders vs Manager, Personas of Leaders & Managers, Connecting

Leaders-Managers with 13 Musical Notes, Trait theory, LSM (Leadership Situational Model), Team Building Models: Tuckman's and Belbin's. Importance of Spatial elements for innovation

#### UNIT-V Understanding Human Desirability

8 hours

Program needed to achieve the comprehensive human goal: the five dimensions of human endeavor (Manaviya Vyavstha) are: Education-Right living (Sikhsa- Sanskar), Health – Self-regulation (Swasthya Sanyam), Justice – Preservation (Nyaya- Suraksha), Production – Work (Utpadan – Karya), Exchange – Storage (Vinimya – Kosh), Darshan-Gyan-Charitra (Shifting the Thinking).

Interconnectedness and mutual fulfilment among the four orders of nature recyclability and self-regulation in nature, Thinking expansion for harmony: Self-exploration (Johari's window), group behaviour, interpersonal behaviour and skills, Myers-Briggs personality types (MBTI), FIROB test to repair relationships.

# Course Outcomes: At the end of this course students will demonstrate the ability to

CO 1	Learn sophisticated design tools to sharpen their problem-solving skills	K2
CO 2	Generate innovate ideas using design thinking tools and converge to feasible idea for breakthrough solution.	K3, K4
CO 3	Implement storytelling for persuasive articulation	K3
CO 4	Understanding the nature of leadership empowerment	K2
CO 5	Understand the role of a human being in ensuring harmony in society and nature.	K2

#### Text books:

- 1. Arun Jain, UnMukt: Science & Art of Design Thinking, 2020, Polaris
- 2. Gavin Ambrose and Paul Harris, Basics Design 08: Design Thinking, 2010, AVA Publishing SA
- 3. R R Gaur, R Sangal, G P Bagaria, A Foundation Course in Human Values and Professional Ethics, First Edition, 2009, Excel Books: New Delhi

#### **Reference Books:**

- 1. Jeanne Liedta, Andrew King and Kevin Benett, Solving Problems with Design Thinking Ten Stories of What Works, 2013, Columbia Business School Publishing.
- 2. Dr RituSoryan, Universal Human Values and Professional Ethics, 2022, Katson Books.
- 3. Vijay Kumar, 101 Design Methods: A Structured Approach for Driving Innovation in Your Organization, 2013, John Wiley and Sons Inc, New Jersey.
- 4. Roger L. Martin, Design of Business: Why Design Thinking is the Next Competitive Advantage, 2009, Harvard Business Press, Boston MA.
- 5. Tim Brown, Change by Design, 2009, Harper Collins.
- 6. Pavan Soni, Design your Thinking: The Mindsets, Toolsets and Skill Sets for Creative Problem-Solving, 2020, Penguin Books.

# NPTEL/ YouTube/ Faculty Video Link:

Unit I h	nttps://www.v	youtube.co	om/watch?v=6	mHCOAAEI8
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https://nptel.ac.in/courses/110106124

https://designthinking.ideo.com/

https://blog.experiencepoint.com/how-mcdonalds-evolved-with-design-thinking

Unit II https://www.coursera.org/lecture/uva-darden-design-thinking-innovation/the-ibm-story-iq0kE

	https://www.coursera.org/lecture/uva-darden-design-thinking-innovation/the-meyouhealth-story-part-i-what-is-W6tTs
	https://onlinecourses.nptel.ac.in/noc19_mg60/preview
Unit III	https://nptel.ac.in/courses/109/104/109104109/
	https://www.d-thinking.com/2021/07/01/how-to-use-storytelling-in-design-thinking/
Unit IV	https://www.worldofinsights.co/2020/10/infographic-8-design-thinking-skills-for-leadership-development/
Unit V	https://www.youtube.com/watch?v=hFGVcx1Us5Y

Course Code	Bachelor of Technology Third Year BEC0511	LTP	Credits
<b>Course Title</b>	Embedded System Design	300	3
Course Objectiv	es: The student will learn about	Bloor	n Level
1	Understand the basic introduction to embedded system design requirements.	]	K1
2	Learn the STM32F401 board & its interfacing.		K2
3	Understand the Architecture of ARM CORTEX-M4 processor.	]	K2
4	Learn the programming techniques of ARM processor.	]	K3
5	Understand the concept of embedded Linux and Linux kernel architecture.		K2
<b>Pre-requisites: F</b>	Knowledge of Microprocessor and Microcontroller	·	
	Course Contents / Syllabus		
UNIT-I	Introduction to Embedded Systems		8 hours
	bedded System, Embedded Systems Vs General Computing Systems, History of Embedded Systems	s, Classification	, Major
	s, Purpose of Embedded Systems, Design Considerations of Embedded Systems.		1
UNIT-II	STM32F401		8 hours
	leo Board, Interfacing with Analog World, Output Devices, Sensors and Actuators, Interfacing with	7 segment LEI	D and LCD
	ing with Temperature Sensor and LDR Light Sensor, Speed Control of DC Motor.		
UNIT-III	Arm Architectures and Processors		8 hours
	arm architectures and processors, Structure and purpose of specific registers in the Arm Cortex-M4		
and Low Power I	t Controller (NVIC), Wakeup Interrupt Controller (WIC), Memory Protection Unit (MPU), Bus Interceptures	erconnect and L	Debug Syster
UNIT-IV	Introduction to Arm Cortex		8 hours
01111-11	g, Compare the C and Assembly programming languages, C as Implemented in Assembly Language,	Panafits and d	0 0 0 10
M/ Programming			
			Tawbacks of
high-level and lo	w-level programming, Introduction to the Mbed Platform and CMSIS, Mbed platform and its import		
high-level and lo UNIT-V	w-level programming, Introduction to the Mbed Platform and CMSIS, Mbed platform and its import  History of Embedded Linux	ance	8 hours
high-level and low UNIT-V Embedded Linux	w-level programming, Introduction to the Mbed Platform and CMSIS, Mbed platform and its import  History of Embedded Linux  versus Desktop Linux, Embedded Linux Distributions, Architecture of Embedded Linux, Linux Kern	ance	8 hours
high-level and low UNIT-V Embedded Linux Up Sequence, GN	w-level programming, Introduction to the Mbed Platform and CMSIS, Mbed platform and its import  History of Embedded Linux	ance	8 hours
high-level and low UNIT-V Embedded Linux Up Sequence, GN	w-level programming, Introduction to the Mbed Platform and CMSIS, Mbed platform and its import  History of Embedded Linux  versus Desktop Linux, Embedded Linux Distributions, Architecture of Embedded Linux, Linux Kern U Cross-p\Platform Tool chain, Linux Serial Driver, Ethernet Driver.	ance	8 hours
high-level and low UNIT-V Embedded Linux Up Sequence, GN Course Outcome	W-level programming, Introduction to the Mbed Platform and CMSIS, Mbed platform and its import  History of Embedded Linux  versus Desktop Linux, Embedded Linux Distributions, Architecture of Embedded Linux, Linux Kern  U Cross-p\Platform Tool chain, Linux Serial Driver, Ethernet Driver.  es: At the end of this course students will demonstrate the ability to	ance nel Architecture	8 hours
high-level and low UNIT-V Embedded Linux Up Sequence, GN Course Outcome CO 1	W-level programming, Introduction to the Mbed Platform and CMSIS, Mbed platform and its import  History of Embedded Linux  versus Desktop Linux, Embedded Linux Distributions, Architecture of Embedded Linux, Linux Kern U Cross-p\Platform Tool chain, Linux Serial Driver, Ethernet Driver.  es: At the end of this course students will demonstrate the ability to  Compute the design considerations of embedded systems.	nel Architecture	8 hours , Linux Star

CO 5	5 Evaluate the concept of embedded Linux and kernel architecture.	K2, K4, K5
Text books:		
1. ARM	system developers guide, Andrew N Sloss, Dominic Symes and Chris Wright, Elsevier, Morgan Kaufman publishers,	2008.
2. The D	Definitive Guide to the ARM Cortex-M3, by Joseph Yiu, 2nd Edition, Newnes, 2009	
3. Embed	edded Linux System Design and Development, P.Raghavan, Amol Lad, Sriram	
Reference Bo	ooks:	
1. Shibu	K V, —Introduction to Embedded Systems, Tata McGraw Hill Education Private Limited, 2009.	
2. Embed	edded Systems: Architecture, Programming and design, Raj Kamal, Second Edition, Tata McGraw Hill publisher, 2010	).
3. David	E. Simon, "An Embedded Software Primer", Pearson Education.	
4. ARM	System-on-Chip Architecture, Steve Furber, Second Edition, Pearson, 2015	
NPTEL/ You	uTube/ Faculty Video Link:	
Unit I	https://www.youtube.com/watch?v=y9RAhEfLfJs	
Unit II	https://www.youtube.com/watch?v=C04ZthY8Yqk	
Unit III	https://nptel.ac.in/courses/106/105/106105193/	
Unit IV	https://www.youtube.com/watch?v=csttt3VHxf8	
Unit V	https://www.youtube.com/watch?v=h-ZP98qhEM8	

Course Code	Bachelor of Technology Third Year BEC0513	LTP	Credits
<b>Course Title</b>	Introduction to Robotics and it's Applications	300	3
<b>Course Objectiv</b>	es: The student will learn about	Bloom L	evel
1	The concept of robotics.	K1	
2	Mathematical relations for forward and inverse kinematic analysis.	K2	
3	The various types of actuators and drive systems.	K1	
4	Different types of sensors for a robot in a specific job task.	К3	
5	The applications of robotics in industry.	K2	
Pre-requisites: E	Engineering mechanics, Basic Electrical & Electronics, Sensor & Instrumentation	I	
	Course Contents / Syllabus		
UNIT-I	Introduction to Robotics		0.1
011111	introduction to Robotics		8 hours
Classification of	Robots, Advantages and Disadvantages of Robots, Robot Components, Robot Degrees of		
Classification of Coordinates, Rob	Robots, Advantages and Disadvantages of Robots, Robot Components, Robot Degrees of Reference Frames, Programming Modes, Robot Characteristics, Robot Workspace, Robot La		
Classification of Coordinates, Rob UNIT-II	Robots, Advantages and Disadvantages of Robots, Robot Components, Robot Degrees of Reference Frames, Programming Modes, Robot Characteristics, Robot Workspace, Robot La Mechanics in Robotics	anguages.	Joints, Robo
Classification of Coordinates, Rob UNIT-II Position Analysi	Robots, Advantages and Disadvantages of Robots, Robot Components, Robot Degrees of Reference Frames, Programming Modes, Robot Characteristics, Robot Workspace, Robot La	anguages. eneous Transformat	Joints, Robo  8 hours ion Matrice
Classification of Coordinates, Rob UNIT-II Position Analysi	Robots, Advantages and Disadvantages of Robots, Robot Components, Robot Degrees of Reference Frames, Programming Modes, Robot Characteristics, Robot Workspace, Robot La Mechanics in Robotics  s – Introduction, Robots as Mechanisms, Conventions, Matrix Representation Homoge	anguages. eneous Transformat	Joints, Robo  8 hours ion Matrice
Classification of Coordinates, Rob UNIT-II Position Analysi Representation of UNIT-III	Robots, Advantages and Disadvantages of Robots, Robot Components, Robot Degrees of Reference Frames, Programming Modes, Robot Characteristics, Robot Workspace, Robot La Mechanics in Robotics  S – Introduction, Robots as Mechanisms, Conventions, Matrix Representation Homoge Transformations Forward and Inverse Kinematics of Robots, Forward and Inverse Kinematics	eneous Transformat of Planar Parallel Re	8 hours ion Matrices obots. 8 hours
Classification of Coordinates, Rob UNIT-II Position Analysi Representation of UNIT-III Introduction, Cha	Robots, Advantages and Disadvantages of Robots, Robot Components, Robot Degrees of Reference Frames, Programming Modes, Robot Characteristics, Robot Workspace, Robot La Mechanics in Robotics  S – Introduction, Robots as Mechanisms, Conventions, Matrix Representation Homoge Transformations Forward and Inverse Kinematics of Robots, Forward and Inverse Kinematics  Introduction to Actuating System	eneous Transformat of Planar Parallel Ro eumatic Devices, Ele	8 hours ion Matrice obots. 8 hours ectric Motors
Classification of Coordinates, Rob UNIT-II Position Analysi Representation of UNIT-III Introduction, Cha	Robots, Advantages and Disadvantages of Robots, Robot Components, Robot Degrees of Reference Frames, Programming Modes, Robot Characteristics, Robot Workspace, Robot Later Mechanics in Robotics  S. – Introduction, Robots as Mechanisms, Conventions, Matrix Representation Homoger Transformations Forward and Inverse Kinematics of Robots, Forward and Inverse Kinematics  Introduction to Actuating System  Transformations of Actuating Systems, Comparison of Actuating Systems, Hydraulic Actuators, Presentation Presentation Forward Robots (Presentation Forward Robots)	eneous Transformat of Planar Parallel Ro eumatic Devices, Ele	8 hours ion Matrice obots. 8 hours ectric Motors
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Classification of Coordinates, Rob UNIT-II Position Analysi Representation of UNIT-III Introduction, Cha Microprocessor C UNIT-IV Introduction, Sen	Robots, Advantages and Disadvantages of Robots, Robot Components, Robot Degrees of Reference Frames, Programming Modes, Robot Characteristics, Robot Workspace, Robot Later Mechanics in Robotics  S — Introduction, Robots as Mechanisms, Conventions, Matrix Representation Homoge Transformations Forward and Inverse Kinematics of Robots, Forward and Inverse Kinematics  Introduction to Actuating System  Transformations of Actuating Systems, Comparison of Actuating Systems, Hydraulic Actuators, Proceedings of Electric Motors, Pulse Width Modulation, Direction Control of DC Motors with an Homogen Sensors	eneous Transformat of Planar Parallel Re eumatic Devices, Ele -Bridge, Speed Redu asors, Force and Pre	8 hours ion Matrice obots. 8 hours ectric Motors action. 8 hours ssure Sensor
Classification of Coordinates, Rob UNIT-II Position Analysi Representation of UNIT-III Introduction, Cha Microprocessor C UNIT-IV Introduction, Sen	Robots, Advantages and Disadvantages of Robots, Robot Components, Robot Degrees of Reference Frames, Programming Modes, Robot Characteristics, Robot Workspace, Robot Late     Mechanics in Robotics	eneous Transformat of Planar Parallel Re eumatic Devices, Ele -Bridge, Speed Redu asors, Force and Pre	8 hours ion Matrice obots. 8 hours ectric Motor action. 8 hours ssure Senso
Classification of Coordinates, Rob UNIT-II Position Analysi Representation of UNIT-III Introduction, Cha Microprocessor C UNIT-IV Introduction, Sen Torque Sensors, I UNIT-V Robotics applica	Robots, Advantages and Disadvantages of Robots, Robot Components, Robot Degrees of Reference Frames, Programming Modes, Robot Characteristics, Robot Workspace, Robot Lateral Mechanics in Robotics  S — Introduction, Robots as Mechanisms, Conventions, Matrix Representation Homoge Transformations Forward and Inverse Kinematics of Robots, Forward and Inverse Kinematics  Introduction to Actuating System  Transformations Systems, Comparison of Actuating Systems, Hydraulic Actuators, Programmer Control of Electric Motors, Pulse Width Modulation, Direction Control of DC Motors with an Homoge Sensors  Sensor Characteristics, Sensor Utilization, Position Sensors, Velocity Sensors, Acceleration Sensors, Wisible Light and Infrared Sensors, Touch and Tactile Sensors, Proximity Sensors	eneous Transformation of Planar Parallel Recumatic Devices, Ele-Bridge, Speed Redusors, Force and Precors, Range Finders, Speed Reductions, Range Finders, Rang	8 hours ion Matrice obots. 8 hours ectric Motors action. 8 hours ssure Senso Sniff Sensor 8 hours

CO 1	Explain the concept of robotics.	K2
CO 2	Formulate the mathematical relations for forward and inverse kinematic analysis.	K2
CO 3	Interpret the various types of actuators and drive systems.	K6
CO 4	Explain the different type's sensor for a robot in a specific job task.	K5
CO 5	Describe the applications of robotics in industry.	K3
Text books:		·
1. Ar	Introduction to Robot Technology, by CoifetChirroza, Kogan Page.	
2. Ro	botic Engineering - An Integrated Approach: Richard D. Klafter Thomas A.	
3. Ro	botics for Engineers, by Y. Koren, McGraw Hill.	
Reference Boo	oks:	
1. Sa	eed B. Niku, "Introduction to Robotics – Analysis, Systems and Application": PHI 2006.	
2. J.J	. Craig, Robotics, Addison-Wesley, 1986.	
3. K.	S Fu, R.C. Gonzalez, C.S.G. Lee, Robotics, McGraw Hill, 1987.	
NPTEL/ You?	Гube/ Faculty Video Link:	
Unit I	https://www.youtube.com/watch?v=y9RAhEfLfJs	
Unit II	https://www.youtube.com/watch?v=C04ZthY8Yqk	
Unit III	https://nptel.ac.in/courses/106/105/106105193/	
Unit IV	https://www.youtube.com/watch?v=csttt3VHxf8	
Unit V	https://www.youtube.com/watch?v=h-ZP98qhEM8	

	Bachelor of Technology Third Year	
<b>Course Code</b>	BEC0512 LTP	Credits
<b>Course Title</b>	Machine Learning 300	3
<b>Course Objective</b>	s: The student will learn about	
The machine learn	ing, basics of statistics, neural networks, dimensionality reduction, various search, optimization and learning tec	hniques.
Pre-requisites: Ba	sics of mathematics and python programming	
-	Course Contents / Syllabus	
UNIT-I	Introduction to Machine Learning	8 hours
Supervised Learni	ng, Unsupervised Learning, Reinforcement Learning and hypothesis testing. Probability Basics, Linear Alg	gebra, Statistic
	Regression & Classification, Bias – Variance, Linear Regression, Multivariate Regression.	,
UNIT-II	Neural Networks	8 hours
Hebb's Rule, McC	ulloch and Pitts Neurons, Limitation of McCulloch and Pitts Neurons, The Perceptron, Linear separability, Li	near Regressio
Rack propagation		
back propagation	algorithm. The Multi-Layer Perceptron (MLP): MLP algorithm, Sequential and Batch training, Amount of train	ng data, numb
	algorithm. The Multi-Layer Perceptron (MLP): MLP algorithm, Sequential and Batch training, Amount of training then to stop training. The network output and errors, Requirements of activation function.	ng data, numo
		8 hours
of hidden layers, w UNIT-III	then to stop training. The network output and errors, Requirements of activation function.	8 hours
of hidden layers, v UNIT-III Linear discriminar	then to stop training. The network output and errors, Requirements of activation function.    Dimensionality Reduction	8 hours
of hidden layers, v UNIT-III Linear discriminar Models: Gaussian	hen to stop training. The network output and errors, Requirements of activation function.    Dimensionality Reduction     tanalysis, Principal Component analysis, Factor analysis, Independent Component analysis, locally linear embed Matrix Models, Nearest Neighbour methods. Support Vector Machine (SVM): Optimal separation, Kernels, Standard Matrix Models, Nearest Neighbour methods.	8 hours
of hidden layers, we will will will will will will will w	hen to stop training. The network output and errors, Requirements of activation function.    Dimensionality Reduction     tanalysis, Principal Component analysis, Factor analysis, Independent Component analysis, locally linear embed Matrix Models, Nearest Neighbour methods. Support Vector Machine (SVM): Optimal separation, Kernels, Standard Matrix Models, Nearest Neighbour methods.	8 hours
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of hidden layers, we UNIT-III Linear discriminary Models: Gaussian Extensions of SVM UNIT-IV Gradient Descent, search, hill climbin UNIT-V	hen to stop training. The network output and errors, Requirements of activation function.    Dimensionality Reduction     tanalysis, Principal Component analysis, Factor analysis, Independent Component analysis, locally linear embed Matrix Models, Nearest Neighbour methods. Support Vector Machine (SVM): Optimal separation, Kernels, Sol.   Optimization and Search     Batch GD, Mini-batch GD, SGD, Going Downhill, least square optimization, conjugate gradients, Exhaustive gradients, Evolutionary Learning: The genetic algorithm, Genetic operators, punctuated equilibrium, The Knapsack Pro     Reinforcement Learning	8 hours Iding, ISOMAI VM algorithm  8 hours e search, Greece blems.  8 hours
of hidden layers, we UNIT-III Linear discriminar Models: Gaussian Extensions of SVM UNIT-IV Gradient Descent, search, hill climbin UNIT-V	Then to stop training. The network output and errors, Requirements of activation function.    Dimensionality Reduction     tanalysis, Principal Component analysis, Factor analysis, Independent Component analysis, locally linear embed Matrix Models, Nearest Neighbour methods. Support Vector Machine (SVM): Optimal separation, Kernels, St.   Optimization and Search     Batch GD, Mini-batch GD, SGD, Going Downhill, least square optimization, conjugate gradients, Exhaustive gradients, Evolutionary Learning: The genetic algorithm, Genetic operators, punctuated equilibrium, The Knapsack Pro-	8 hours Iding, ISOMAI VM algorithm  8 hours e search, Greece blems.  8 hours
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of hidden layers, we UNIT-III Linear discriminar Models: Gaussian Extensions of SVN UNIT-IV Gradient Descent, search, hill climbin UNIT-V State and action sp Classification and feature map, Simu	Then to stop training. The network output and errors, Requirements of activation function.    Dimensionality Reduction     tanalysis, Principal Component analysis, Factor analysis, Independent Component analysis, locally linear embed Matrix Models, Nearest Neighbour methods. Support Vector Machine (SVM): Optimal separation, Kernels, St.   Optimization and Search     Batch GD, Mini-batch GD, SGD, Going Downhill, least square optimization, conjugate gradients, Exhaustive gradients. Evolutionary Learning: The genetic algorithm, Genetic operators, punctuated equilibrium, The Knapsack Pro     Reinforcement Learning     aces, the reward function, Markov chain decision process, Uses of Reinforcement Learning. Learning with trees regression tree, Random Forest. Unsupervised Learning: The k-means algorithm, Vector quantization, The search process.	8 hours  Iding, ISOMAl VM algorithm  8 hours e search, Greece blems.  8 hours  Decision Tree
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of hidden layers, we UNIT-III Linear discriminary Models: Gaussian Extensions of SVM UNIT-IV Gradient Descent, search, hill climbin UNIT-V State and action spectate and action and feature map, Simu	hen to stop training. The network output and errors, Requirements of activation function.    Dimensionality Reduction     tanalysis, Principal Component analysis, Factor analysis, Independent Component analysis, locally linear embed Matrix Models, Nearest Neighbour methods. Support Vector Machine (SVM): Optimal separation, Kernels, S. M.   Optimization and Search     Batch GD, Mini-batch GD, SGD, Going Downhill, least square optimization, conjugate gradients, Exhaustive ag. Evolutionary Learning: The genetic algorithm, Genetic operators, punctuated equilibrium, The Knapsack Pro Reinforcement Learning     Reinforcement Learning     aces, the reward function, Markov chain decision process, Uses of Reinforcement Learning. Learning with trees regression tree, Random Forest. Unsupervised Learning: The k-means algorithm, Vector quantization, The stated annealing.    At the end of this course students will demonstrate the ability to	8 hours  ding, ISOMA  VM algorithm  8 hours  search, Greed blems.  8 hours  Decision Tree  elf-organization
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of hidden layers, we UNIT-III Linear discriminar Models: Gaussian Extensions of SVN UNIT-IV Gradient Descent, search, hill climbin UNIT-V State and action sp Classification and feature map, Simu Course Outcomes  CO 1 CO 2	hen to stop training. The network output and errors, Requirements of activation function.    Dimensionality Reduction     tanalysis, Principal Component analysis, Factor analysis, Independent Component analysis, locally linear embed Matrix Models, Nearest Neighbour methods. Support Vector Machine (SVM): Optimal separation, Kernels, St.    Optimization and Search     Batch GD, Mini-batch GD, SGD, Going Downhill, least square optimization, conjugate gradients, Exhaustive ag. Evolutionary Learning: The genetic algorithm, Genetic operators, punctuated equilibrium, The Knapsack Proceeding Reinforcement Learning aces, the reward function, Markov chain decision process, Uses of Reinforcement Learning. Learning with trees regression tree, Random Forest. Unsupervised Learning: The k-means algorithm, Vector quantization, The stated annealing.    At the end of this course students will demonstrate the ability to	8 hours Iding, ISOMA VM algorithm  8 hours search, Gree blems.  8 hours Decision Tree elf-organization  K1 K3

Text books:	
1. Stephen Marsland, "Machine Learing- An Algorithm Perspective", CRC Press, 2nd edition.	
2. EthemAlpaydin, —Introduction to Machine Learning (Adaptive Computation and Machine Learning), The Machine Learning (Adaptive Computation and Machine Learning)	MIT Press 2004.
3. SimanHaykin, "Neural Netowrks", Prentice Hall of India	
4. D.E. Goldberg, "Genetic Algorithms: Search, Optimization and Machine Learning", Addison Wesley	
Reference Books	
1. Kumar Satish, "Neural Networks", Tata Mc Graw Hill	
2. Timothy J. Ross, "Fuzzy Logic with Engineering Applications", Wiley India.	
3. Bishop, C., Pattern Recognition and Machine Learning. Berlin: Springer-Verlag.	
4. An Introduction to Genetic Algorithms, Melanie Mitchell, MIT Press, 2000.	
NPTEL/ YouTube/ Faculty Video Link:	
Unit I https://www.youtube.com/watch?v=T3PsRW6wZSY&list=PLJ5C_6qdAvBGaabKHmVbtryZW9KpICiB	НС
Unit II https://www.youtube.com/watch?v=T3PsRW6wZSY&list=PLJ5C_6qdAvBGaabKHmVbtryZW9KpICiB	НС
Unit III https://www.youtube.com/watch?v=T3PsRW6wZSY&list=PLJ5C_6qdAvBGaabKHmVbtryZW9KpICiB	НС
Unit IV https://www.youtube.com/watch?v=T3PsRW6wZSY&list=PLJ5C_6qdAvBGaabKHmVbtryZW9KpICiI	HC
Unit V https://www.youtube.com/watch?v=T3PsRW6wZSY&list=PLJ5C_6qdAvBGaabKHmVbtryZW9KpICiI	НС

	Bachelor of Technology Third Year		
Course Code	BEC0514	LTP	Credits
Course Title	Artificial Intelligence	300	3
Course Objectives:	The student will learn about		

The various aspect of Artificial Intelligence. They will learn AI towards problem solving inference, perception and knowledge representation. They will be able to demonstrate knowledge about intelligent systems by assembling solutions to concrete computational problems. They will acquire the knowledge of various forms of learning and computation statistics.

**Pre-requisites:** Basic knowledge of Mathematics, Python, C++, Computational Intelligence

# **Course Contents / Syllabus**

# UNIT-I Introduction to Artificial Intelligence

8 hours

Historical developments of Artificial Intelligence, well defined learning problems, designing a Learning System. Intelligent Agents: Characteristics of Intelligent Agents, Typical Intelligent Agents, Problem Solving Approach to Typical AI problems.

### UNIT-II Search Strategies

8 hours

Uninformed Search Strategies: DFS, BFS, Informed Search Strategies: Local search algorithms and optimistic problems, adversarial Search, Search for games, minimax, Alpha - Beta pruning, Heuristic Search techniques, Hill Climbing, Best-first search, Problem reduction, Constraint satisfaction, Means Ends Analysis, Iterative deepening Heuristic Search and A\*.

## UNIT-III Introduction to Logic

8 hours

Propositional Logic Concepts, Semantic Tableaux and Resolution Propositional logic, FOPL, Semantic Tableaux and Resolution in FOPL, Logic Programming in Prolog. Production systems and rules for some AI problems: Water Jug Problem, Missionaries-Cannibals Problem, n-Queen problem, monkey banana problem, Travelling Salesman Problem. Knowledge representation, semantic nets, partitioned nets, parallel implementation of semantic nets. Frames, Common Sense reasoning and thematic role frames.

### UNIT-IV Expert Systems

8 hours

Architecture of Knowledge-Based System, Rule-based systems, Forward and Backward Chaining, Frame Based systems. Architecture of Expert System, Forward & Backward chaining, Resolution, Probabilistic reasoning, Utility theory, Hidden Markov Models (HMM), Bayesian Networks

#### UNIT-V Optimization Techniques

8 hours

Planning with state Space Search, Conditional Planning, Continuous planning, Multi-Agent Planning, Forms of learning, inductive learning, Reinforcement Learning, learning decision trees, Neural Net learning, and Genetic learning. Probabilistic Methods, Bayesian Theory, Dempster Shafer Theory, Bayes Network. Evolutionary computation: Swarm Intelligence, ant colony optimization. Case Study: Health Care, E-Commerce, Smart Cities.

Course Outcomes: At the end of this course students will demonstrate the ability to

CO 1	Elaborate historical perspective of AI and its foundations.	K1
CO 2	Apply principles of AI toward problem solving and drawing inference thereof.	K4
CO 3	Describe perception, knowledge representation, and different learning techniques.	К3
CO 4	Implement architecture of knowledge-Based System, Rule-based systems, and other expert systems.	K5
CO 5	Apply evolutionary computational algorithms and different search algorithms.	K5
Text books		
1. Stu	art Russell, Peter Norvig, "Artificial Intelligence-A Modern Approach", Pearson Education. Fourth Edition 2021	
2. Ela	ine Rich and Kevin Knight, "Artificial Intelligence", McGraw-Hill 3 <sup>rd</sup> Edition 2010.	
Reference Boo	ks	
1. Pat	rick Henry Winston, "Artificial Intelligence", Pearson Education Inc., Third edition.	
	hon Machine Learning: Learn Pythonina Week and Master It. A Hands-On Introduction to Artificial Intelligence Cod	ling, a Project
Bas	sed Guide with Practical Exercises (7 Days Crash Course, Book2) 2020.	
NPTEL/ YouT	Cube/ Faculty Video Link:	
Unit I	https://nptel.ac.in/courses/106102220	
Unit II	https://nptel.ac.in/courses/106102220	
Unit III	https://nptel.ac.in/courses/106102220	
Unit IV	https://nptel.ac.in/courses/106102220	

Unit V

https://nptel.ac.in/courses/106102220

Bachelor of Technology Third Year				
Course Code	BEC0515	LTP	Credits	
Course Title	VLSI Technology	300	3	
O OI 4 T				

#### Course Objectives: The student will learn about

An introduction to the principles and processes of microfabrication, with a focus on semiconductor materials and devices. Students will learn about the key steps in microfabrication, such as photolithography, etching, deposition, and diffusion. They will also learn about the properties of semiconductor materials and how they are used to fabricate electronic devices.

**Pre-requisites:** Basic knowledge of Semiconductor materials

#### **Course Contents / Syllabus**

UNIT-I Introduction to VLSI Technology 8 hours

Environment for VLSI Technology: Clean room and safety requirements. Wafer cleaning processes and wet chemical etching techniques. Impurity incorporation: Solid State diffusion modelling and technology; Ion Implantation modelling, technology and damage annealing; characterization of Impurity profiles.

UNIT-II Oxidation Techniques 8 hours

Epitaxy: Vapor-Phase Epitaxy, Molecular Beam Epitaxy, Silicon on Insulators, Epitaxial Evaluation Oxidation: Growth Kinetics, Thin Oxides, Oxidation Techniques and Systems, Oxides Properties.

UNIT-III Lithography 8 hours

Optical Lithography, Electron beam lithography, Photo masks, Wet Chemical Etching. Dielectric and Polysilicon Film Deposition: CVD techniques for deposition of Polysilicon, Silicon Dioxide, Silicon Nitride.

UNIT-IV Diffusion 8 hours

Models of diffusion in solids, Fick's 1-Dimensional diffusion equation, Diffusion of Impurities in Silicon and Silicon Dioxide, Diffusion Equations, Diffusion Profiles, Diffusion Furnace, Solid, Liquid and Gaseous Sources. Ion-Implantation: Ion-Implantation Technique, Range Theory, Implantation Equipment.

UNIT-V CMOS Fabrication Techniques

8 hours

Metal film deposition, Metallization: Metallization Application, Metallization Choices, Evaporation and sputtering techniques, Physical Vapor Deposition, Vacuum Deposition. Failure mechanisms in metal interconnects; multi-level metallization schemes. CMOS fabrication steps.

Course Outcomes: At the end of this course students will demonstrate the ability to

CO 1	Understand the basic principles of microfabrication	K4		
CO 2	CO 2 Design and implement microfabrication processes K3			
CO 3	CO 3 Characterize semiconductor materials and devices			
CO 4 Apply microfabrication techniques to fabricate electronic devices		К3		
CO 5	CO 5 Know the safety issues involved in the fabrication process.			
Text books:				
1. Jac	eger, R. C. (2002). Introduction to microelectronic fabrication (2nd ed.). Upper Saddle River, NJ: Prentice Hall.			
2. Sz	e, S. M., & Kwok, K. N. (2006). Physics of semiconductor devices (3rd ed.). Hoboken, NJ: Wiley			
Reference Boo				
	e, S. M. (1981). VLSI technology (2nd ed.). New York, NY: McGraw-Hill.			
2. Ma	ndou, M. J. (2002). Fundamentals of microfabrication (2nd ed.). Boca Raton,FL: CRC Press			
NPTEL/ You?	Tube/ Faculty Video Link:			
Unit I	https://archive.nptel.ac.in/noc/courses/noc15/SEM1/noc15-ec02/			
Unit II	https://video.search.yahoo.com/search/video;_ylt=AwrjbCfLAhtoPicCgpRXNyoA;_ylu=Y29sbwNncTEEcG9zAzEEc	dnRpZAMEc		
	2VjA3BpdnM-?p=VLSI+Technology&fr2=piv-web&type=E210US826G0&fr =mcafee#id=7&vid= 5e694387d3485	7a70efe44 d2		
	5f2595c7&action=view			
Unit III	https://video.search.yahoo.com/search/video;_ylt=AwrjbCfLAhtoPicCgpRXNyoA;_ylu=Y29sbwNncTEEcG9zAzEEc	dnRpZAMEc		
	2VjA3BpdnM-?p=VLSI+Technology&fr2=piv-web&type=E210US826G0&fr=mcafee#id=15&vid=5fa3bdf0 373ac3	724665542b		
	dfb6fb3d&action=view			
Unit IV	https://nptel.ac.in/courses/117101106			
Unit V	https://www.youtube.com/watch?v=Mkt02iiCcYY			

Bachelor of Technology Third Year				
Course Code	BEC0551	LTP	Credits	
Course Title	Wireless Communication	006	3	
C Obi4' 7	DL4 14			

Course Objectives: The student will learn about

The evolution of wireless communication technologies from 1G to 5G, emphasizing the terminology, system requirements, and design goals that have driven advancements in cellular networks. It covers LTE and its progression to LTE-Advanced, as well as alternative technologies like WiMAX. Students will gain a solid foundation in radio wave propagation, wireless channel modeling, and fading phenomena, including MIMO systems and various statistical models. The course explores multiple access schemes such as FDMA, TDMA, CDMA, and OFDM, and addresses challenges in wireless and ad-hoc networks including security, energy efficiency, and cross-layer design. Emerging technologies such as small cells, cognitive radio, smart antennas, and software-defined radio are examined for their roles in enhancing spectrum efficiency and network capacity. Furthermore, the course delves into WLAN standards (IEEE 802.11 family), and other wireless technologies, providing insight into the design, implementation, and future direction of next-generation wireless communication systems.

Pre-requisites: Analog and Digital Communication

### **Course Contents / Syllabus**

UNIT-I Introduction to Wireless Communication 8 hours

Introduction to 1G/2G/3G/4G/5G Terminology. Evolution of cellular systems requirements, goals, and vision of the next-generation wireless communication systems, Requirements and Targets for Long Term Evolution (LTE) - Technologies for LTE-4G Advanced Features and Roadmap Evolutions from LTE to LTEA. WiMAX.

# UNIT-II Introduction to Radio Wave Propagation

8 hours

Introduction to Radio Wave Propagation, Free Space Propagation Model, wireless channel models- path loss and shadowing models; statistical fading models; narrowband and wideband fading models; MIMO channels, Narrowband fading, Wideband fading models, Delay spread and Coherence bandwidth, Doppler spread and Coherence time, Flat fading versus frequency selective fading, Slow fading versus fast fading, Discrete-time model. AWGN.

# UNIT-III Access Schemes

8 hours

Contention-free multiple access schemes (FDMA TDMA, CDMA, SDMA, and Hybrid), contention- based multiple access schemes (ALOHA and CSMA), Waveforms, Variable subcarrier spacing, supported transmission numerologies. Design Challenges in Ad-hoc wireless networks, the concept of cross-layer design, security in wireless networks, energy-constrained networks, MANET and WSN.

#### UNIT-IV Introduction to OFDM

8 hours

Small cells: Past, present, and future trends of cellular networks coverage and capacity of small cellnetworks, Data transmission using multicarrier modulation for frequency-selective fading channels. Overlapping sub channels, Mitigation of Subcarrier Fading, Discrete Implementation of multicarrier — OFDM. Cyclic prefix, Peak-to average-power-ratio. Multicarrier modulation, OFDM, diversity multiplexing trade-off, OFDM system, smart-antenna: beam forming, cognitive radio, software-defined radio, communication relays, spectrum sharing.

# UNIT-V Introduction to LTE

8 hours

Introduction to LTE, LTE-A Standards and Technology, WLAN Standard IEEE 802.11, IEEE 802.11 Medium Access Control, Comparison of IEEE 802.11 a,b,g and n standards, IEEE 802.16 and its enhancements.

Course Outcomes: At the end of this course students will demonstrate the ability to		
CO 1	Understand the network performance.	K2
CO 2	Understand 5G Handover procedure.	K2
CO 3	Analyze the relation between beamforming, gain and antenna count.	K4
CO 4	Understand and analyze different Physical layer parameters.	K4
CO 5	Investigate path losses.	K3

# **Text Books:**

- 1. T. S. Rappaport, R. W. Heath Jr., R. C. Daniels, and J. M. Murdock, Millimeter Wave Wireless Communication., Pearson Education, 2015.
- 2. Andrea Goldsmith, "Wireless Communications", Cambridge University Press, 2005.

#### **Reference Books:**

1. Vijay K Garg, "Wireless Communications and Networks", Morgan Kaufmann Publishers an Imprint of Elsevier, USA 2009 (Indian reprint)

# Links: NPTEL/You Tube/Web Link

Unit I	https://www.youtube.com/watch?v=d7zeaz-NjmM
Unit II	https://www.youtube.com/watch?v=9ujT1upyWVg
Unit III	https://www.youtube.com/watch?v=AKXFwwcww_E
<b>Unit IV</b>	https://www.youtube.com/watch?v=ew0lx9buuXc
Unit V	https://www.youtube.com/watch?v=pnunzdvezto

# **List of Practical:**

S.No	Name of Experiment	CO Mapping
1	Understand Measures of Network Performance: Throughput and Delay.	CO1
2	Simulate and study 5G Handover procedure.	CO1
3	Simulate and analyze the relation between beamforming gain and antenna count.	CO4
4	Investigate how throughput varies with antenna count.	CO5
5	Investigate how a packet is transmitted over OFDM physical layer.	CO4
6	Analytically estimate (per 3GPP standards) the application throughput for asimple use-case.	CO2
7	Simulate and analyze throughput as different PHY parameters are varied.	CO2
8	Analytically estimate (per 3GPP standards) the application throughput for a simple use-case.	CO3

9	Simulate path loss variation with the distance between the UE and the gNB.	CO4
10	Investigate path loss variation with gNB height. What is the optimal height of a gNB?	CO5
11	To calculate no of channel in FDMA.	CO3
12	To calculate allocated bandwidth for given specification.	CO3
13	To calculate efficiency in TDMA system.	CO3
14	To calculate channel capacity of SISO.	CO4
15	To calculate channel capacity of single input multiple output.	CO4
16	To calculate channel capacity of SIMO with N=40.	CO4
17	To calculate channel capacity of multiple input and single output(MISO) system.	CO4
18	To calculate the channel capacity of MISO of receiver.	CO4
19	To calculate channel capacity of MIMO system.	CO4
20	To calculate the channel capacity of MIMO with different no of receiver and transmitter.	CO4
21	To calculate the channel capacity of SISO system if bandwidth of channel is 1MHZ and SNR is 24db.	CO4
22	To calculate no of channel in FDMA system.	CO3
23	To calculate Allocated BW "Bt" given N, Bc and Bg for a wireless system.	CO2
24	To calculate time in transmitting 1bit of data.	CO2
25	To calculate rate of transmission of data if no of bit and time is given.	CO2
26	To compute total frame efficiency in TDMA system.	CO3
27	To compute the total no of overhead bits(Nov) of TDMA system if eff is given.	CO3
28	To calculate vulnerable time for pure aloha.	CO3
29	To calculate the vulnerable time for slotted aloha.	CO3
30	To calculate the throughput in KBPS for pure aloha.	CO3
31	To calculate no of station given other parameters of pure aloha.	CO3
32	To calculate the no of frame per second by each station.	CO3
33	To calculate the coherent time in Doppler shift.	CO2
34	To calculate the no of channel in pure aloha.	CO3
35	To calculate the maximum throughput of pure aloha given BW.	CO3
36	To calculate the throughput of each station of if probability of each is given.	CO3

37	To find AMPS communication level.	CO1
38	To find comparison of capacity.	CO1
39	To find Capacity of GSM.	CO5
40	To find frame duration.	CO5

	Bachelor of Technology Third Year		
Course Code	BEC0552	LTP	Credits
Course Title	Computer Networks	006	3
Course Objective	es: The student will learn about		- 1
	king, different components of computer networks, various protocols, modern technologies, fut, by applying these knowledge students can design, develop and analysed various types of networks.	ure networ	king and thei
	sic knowledge of Digital system design and Computer System.		
<b></b>	Course Contents / Syllabus		
UNIT-I	Introduction to Network Model		8 hours
	OSI Model, TCP/IP reference model, Network devices, Mode of communications		
	Network topology design, Types of LAN, wired networking media (LAN cables, and OFC), transmissi	on impairm	ents. Switching
techniques, IEEE			
<u> </u>	Framing, Error Detection and Correction codes, Flow control protocols, Channel allocation, Multiple	access proto	ocols.
UNIT-II	Network and Transport Layer		8 hours
Network Laver: I	Logical addressing, Basic internetworking (IP, CIDR, ARP, RARP, DHCP, ICMP), IPv4, Subnetting	g. Routing.	forwarding and
	dynamic routing, Routing algorithms and protocols, Congestion control algorithms.	5,6,	
	Process-to-process delivery, Transport layer protocols (UDP and TCP), Connection manage	ement, Flo	w control and
_	ndow management, TCP Congestion control, Quality of service.	,	
UNIT-III	Virtual Private Network		8 hours
Application Laver	: Web and HTTP, E-mail, DNS, Socket programming with TCP and UDP. DNS, electronic mail, Wor	ld Wide We	_
			<ul><li>b: architectura</li></ul>
	web document and http.	10 11100 110	b: architectura
, <b>,</b>	web document and http. etwork: VPNIntroduction to VPNs, VPN protocols and encryption algorithms, OpenVPN installation		
Virtual Private No	etwork: VPNIntroduction to VPNs, VPN protocols and encryption algorithms, OpenVPN installation		
, <b>,</b>	etwork: VPNIntroduction to VPNs, VPN protocols and encryption algorithms, OpenVPN installation		
Virtual Private Ne communication usi UNIT-IV	etwork: VPNIntroduction to VPNs, VPN protocols and encryption algorithms, OpenVPN installation ng Open VPN.    Modern Networking	n and config	uration, Secure
Virtual Private No communication usi UNIT-IV Next Generation I	etwork: VPNIntroduction to VPNs, VPN protocols and encryption algorithms, OpenVPN installation on the open VPN.    Modern Networking   Modern Networking     P: IPv4 vs. IPv6, Representation, address space, IPv6 header format, IPv6 extension, IPv6 routing are	n and config	uration, Secure  8 hours
Virtual Private Necommunication usi UNIT-IV Next Generation I configuration, renu	etwork: VPNIntroduction to VPNs, VPN protocols and encryption algorithms, OpenVPN installation ng Open VPN.    Modern Networking	n and config	uration, Secure  8 hours
Virtual Private Note Communication usi UNIT-IV Next Generation I configuration, renule header, QOS.	etwork: VPNIntroduction to VPNs, VPN protocols and encryption algorithms, OpenVPN installation on the open VPN.    Modern Networking   Modern Networking     P: IPv4 vs. IPv6, Representation, address space, IPv6 header format, IPv6 extension, IPv6 routing are	n and config chitecture, A Packet forma	8 hours  auto  t, Extension
Virtual Private Necommunication usi UNIT-IV Next Generation I configuration, renu header, QOS. Modern Networki	etwork: VPNIntroduction to VPNs, VPN protocols and encryption algorithms, OpenVPN installation of Open VPN.    Modern Networking     P: IPv4 vs. IPv6, Representation, address space, IPv6 header format, IPv6 extension, IPv6 routing are mbering, Transition from IPv4 to IPv6- Dual stack, Tunneling, Header, Translation IPv6, Protocol- IPv6- Dual stack, Tunneling, Header, Translation IPv6- Protocol- IPv	chitecture, APacket forma	8 hours  auto  t, Extension
Virtual Private Necommunication usi UNIT-IV Next Generation I configuration, renu header, QOS. Modern Networki	etwork: VPNIntroduction to VPNs, VPN protocols and encryption algorithms, OpenVPN installation of Open VPN.    Modern Networking	chitecture, APacket forma	8 hours  8 toto  at, Extension
Virtual Private Note Communication using UNIT-IV Next Generation I configuration, renumber QOS. Modern Networki Protocols, Open Flou UNIT-V	etwork: VPNIntroduction to VPNs, VPN protocols and encryption algorithms, OpenVPN installation of Open VPN.    Modern Networking	chitecture, A Packet forma er, Switch de ecture.	8 hours  auto at, Extension esign, Switch  8 hours
Virtual Private Necommunication using UNIT-IV  Next Generation Inconfiguration, renulheader, QOS.  Modern Networking Protocols, Open Flourit-V  Softwarized and	etwork: VPNIntroduction to VPNs, VPN protocols and encryption algorithms, OpenVPN installation of Open VPN.    Modern Networking	chitecture, A Packet forma er, Switch de ecture.	8 hours  auto at, Extension esign, Switch  8 hours
Virtual Private Necommunication usi UNIT-IV Next Generation I configuration, renu header, QOS. Modern Networki Protocols, Open Flo UNIT-V Softwarized and Serverless comput	etwork: VPNIntroduction to VPNs, VPN protocols and encryption algorithms, OpenVPN installation of Open VPN.    Modern Networking	chitecture, A Packet forma er, Switch de ecture.	8 hours  auto at, Extension esign, Switch  8 hours
Virtual Private Necommunication usi UNIT-IV Next Generation I configuration, renu header, QOS. Modern Networki Protocols, Open Flo UNIT-V Softwarized and Serverless comput	etwork: VPNIntroduction to VPNs, VPN protocols and encryption algorithms, OpenVPN installation of Open VPN.    Modern Networking	chitecture, A Packet forma er, Switch de ecture.	8 hours  auto at, Extension esign, Switch  8 hours

CO 3	Design and evaluate the various network connections using modern tool.	K4
CO 4	Demonstration and implementation of the VLAN and.	K3
CO 5	Examine the P4 language for various purposes.	K5

#### **Text Books:**

- 1. Behrouz Forouzan, "Data Communication and Networking" Fourth Edition-2006, Tata McGraw Hill.
- 2. Andrew Tanenbaum "Computer Networks", Fifth Edition-2011, Prentice Hall.
- 3. William Stallings, "Data and Computer Communication", Eighth Edition-2008, Pearson.

#### **Reference Books:**

- 1. Kurose and Ross, "Computer Networking- A Top-Down Approach", Eighth Edition-2021, Pearson.
- 2. Peterson and Davie, "Computer Networks: A Systems Approach", Fourth Edition-1996, Morgan Kaufmann
- 3. Software-Defined Networks: A Systems Approach, Peterson, Cascone, O'Connor, Vachuska, and Davie, Online Free Reference Book available at <a href="https://sdn.systemsapproach.org/index.html">https://sdn.systemsapproach.org/index.html</a>
- 4. Cloud Networking: Understanding Cloud-based Data Centre Networks, Gary Lee (Author), Morgan Kaufmann (Publisher), 2014,ISBN-139780128007280

# Links: NPTEL/You Tube/Web Link

Unit I	https://www.youtube.com/watch?v=LX_b2M3IzN8, https://www.youtube.com/watch?v=LnbvhoxHn8M
Unit II	https://www.youtube.com/watch?v=uwoD5YsGACg, https://www.youtube.com/watch?v=ddM9AcreVqY
Unit III	https://www.youtube.com/watch?v=qZlMS4yJM-E
Unit IV	https://www.youtube.com/watch?v=FkaFr3cpg6U, https://www.youtube.com/watch?v=CaukSKg_sI0
Unit V	https://www.youtube.com/watch?v=CWQUI7zw9ac , https://www.youtube.com/watch?v=6kPqzgPiz8w

### **List of Practical:**

S.No	Name of Experiment	CO Mapping
1	Study of cables, tools, connectors etc used in networking.	CO1
2	Study of Network Devices.	CO1
3	Test the Network connection using ping, ipconfig etc command.	CO1
4	Implementation of netstat, treert etc command for network connection.	CO1
5	Build and test simple network using UTP cable (crossover and straight), network devices and a hub based topology.	CO1
6	Build and test simple network using UTP cable (crossover and straight), network devices and a bus topology.	CO1

7	Build and test simple network using UTP cable (crossover and straight), network devices and a ring topology.	CO1
8	Build and test simple network using UTP cable (crossover and straight), network devices and a mesh topology.	CO1
9	Build and test simple network using UTP cable (crossover and straight), network devices and a hybrid topology.	CO1
10	Build and test simple network using UTP cable (crossover and straight), network devices and a tree topology.	CO1
11	Implementation of data link layer framing method for bit stuffing in any language like C++, Java or Python.	CO2
12	Implementation of data link layer framing method for byte stuffing in any language like C++, Java or Python.	CO2
13	Implementation of data link layer framing method for character count in any language like C++, Java or Python.	CO2
14	Implementation of data link layer for frame size framing in any language like C++, Java or Python.	CO2
15	Implementation of VRC algorithm in any language like C++, Java or Python.	CO2
16	Implementation of LRC algorithm in any language like C++, Java or Python.	CO2
17	Implementation of Checksum algorithm in any language like C++, Java or Python.	CO2
18	Implementation of CRC algorithm in any language like C++, Java or Python.	CO2
19	Construction of Hamming code (7, 4) code any language like C++, Java or Python.	CO2
20	Detection of Hamming code (7, 4) code any language like C++, Java or Python.	CO2
21	Correction of Hamming code (7, 4) code any language like C++, Java or Python.	CO2
22	Implementation of simplest protocol in any language like C++, Java or Python.	CO2
23	Implementation of stop and wait protocol in any language like C++, Java or Python.	CO2
24	Implementation of stop and wait ARQ protocol in any language like C++, Java or Python.	CO2
25	Implementation of sliding window protocol in any language like C++, Java or Python.	CO2
26	Implementation of Go –Back –N- ARQ protocol in any language like C++, Java or Python.	CO2
27	Implementation of Selective Repeat ARQ protocol in any language like C++, Java or Python.	CO2
28	Implementation of Caesar cipher technique & RSA algorithm in any language like C++, Java or Python.	CO2
29	Write a program in java to find the IP address of the system.	CO2
30	Write a program in java to find the IP address of the any site if name is given.	CO2
31	Write a C/C++ program to determine if the IP address is in Class A, B, or C.	CO2
33	Write a C/C++ program to translate dotted decimal IP address into 32 bit address.	CO2
34	Write a C/C++ program to determine if the IP address is in Class A, B, C, D, or E.	CO2
35	Implement Dijkstra's algorithm to compute the Shortest path through a graph.	CO3

36	Take an example subnet graph with weights indicating delay between nodes. Now obtain Routing table art each node using distance vector routing algorithm.	CO3
37	. Take an example subnet of hosts. Obtain broadcast tree for it.	CO3
38	Create a socket for HTTP for web page upload and download	CO3
39	Study and implement model for Socket Programming and Client – Server model.	CO3
40	Experimental study of application protocols such as HTTP, FTP,SMTP, using network packet sniffers and analyzers such as Wireshark. Small exercises in socket programming in C/C++/Java	CO3
41	Set up IPv6 networks and configure devices to communicate using IPv6 addresses.	CO3
42	set up a network with multiple devices, assign QoS policies to different traffic flows (e.g., voice, video, data), and measure the impact of QoS on performance metrics such as latency, packet loss, and throughput.	CO3
43	Introduction to CISCO Packet Tracer.	CO3
44	Performing an Initial Switch Configuration	CO3
45	Performing an Initial Router Configuration	CO3
46	Connect the computers in Local Area Network.	CO3
47	Configuring and Troubleshooting a Switched Network	CO3
48	Design a Bus Topology and check the connectivity using ping command.	CO3
49	Design a Star Topology and check the connectivity using ping command.	CO3
50	Design a Mesh Topology and check the connectivity using ping command.	CO3
51	Design a Ring Topology and check the connectivity using ping command.	CO3
52	Design a Hybrid Topology and check the connectivity using ping command.	CO3
53	Configuring and Troubleshooting a Switched Network on simulator.	CO3
54	Configuring Wired Equivalent Privacy (WEP) on a Wireless Router on simulator.	CO3
55	Examining WAN Connections on simulator.	CO3
56	Examining Network Address Translation (NAT) on simulator.	CO3
57	Configuring a Cisco Router as a DHCP Server.	CO3
58	Demonstration of Connection management using Network Simulator.	CO3
59	Demonstration of Flow control and retransmission using Network Simulator.	CO3
60	Demonstration of Window management using Network Simulator.	CO3
61	Demonstration of TCP Congestion control using Network Simulator.	CO3
62	Demonstration of Application layer protocols using Network Simulator.	CO3

63	Setting up a Virtualized Network Environment using VMware.	CO4
64	Introduction to openflow controller	CO4
65	Perform the network segmentation using VLANS	CO4
66	Introduction to SDN controllers.	CO4
67	Traffic engineering with SDN	CO4
68	Network monitoring and Traffic analysis.	CO4
69	Network Function Virtualization with SDN	CO4
70	Familiarize students with the P4 language syntax and concepts.	CO5
71	Design and implement a simple P4 program to process packets at the data plane.	CO5
72	Define match-action tables, packet parsing, and forwarding rules.	CO5
73	Implement a P4 program to classify network traffic based on different criteria (e.g., source/destination IP, port numbers).	CO5
74	Implement packet sampling techniques for capturing statistics and monitoring network performance.	CO5
75	Develop a mini project based on programming/ simulator skills.	

	Bachelor of Technology Third Year		
Course Code	BEC0511P	LTP	Credits
Course Title	Embedded System Design Lab	004	2
<b>Course Objectiv</b>	es: The student will learn about	Bloom's	Level
1	Writing different programs for Arm based microcontroller.	K3	
2	Freedom KL25Z board to build a system.	K5	
3	Arm-based embedded system, and program to satisfy given user specifications.	K5	
4	Commercial tools to develop Arm-based embedded systems.	K2	,
5	Commercial API and tools to accelerate the development cycle of Arm-based embedded	K4	
	systems.		
<b>Pre-requisites:</b> B	Basics of Microprocessor and Microcontroller		
	List of Experiments		
S.No	Name of Experiment		CO
1	Describe architecture and Pin diagram of Freedom KL25Z board.		CO2
2	Write and compile the code to perform the arithmetic operations in ARM thumb instruction set.		CO1
3	Write and compile the code to perform logical operations in ARM thumb instruction set.		CO3
4	Write and compile code to perform Shift operations in ARM instruction set.		CO3
5	Write an assembly code subroutine to approximate the square root of an argument using the bis	ection method.	CO3
6	Write the Thumb code to multiply the two 32-bit in memory at addresses 0x1234_5678 and storing the result in address 0x2000_0010.	l 0x7894_5612,	CO2
7	Write and compile assembly code and debug the program image on a mbed board (name KL25Z board) using the Keil MDK-ARM tool.	y the Freedom	CO4
8	Write a program to configure a General-Purpose Input Output (GPIO) peripheral in a low-level in practice.	(register-level)	CO3
9	Write and compile assembly code of I/O interfacing and debug the program image on a KL25Z Keil MDKARM tool. Interface LEDs and Switches.	board using the	CO5
10	Write and compile assembly code of Sensor interfacing and debug the program image on an KL2 the Keil MDK-ARM tool. Interface PIR sensor-and DHT sensor.	25Z board using	CO5
Course Outcome	e: After successful completion of this Lab students will be able to		Blooms Level
CO 1	Write a program for Arm based microcontroller.		K1
CO 2	Analyze Freedom KL25Z board to build a system.		K4
CO 3	Build an Arm-based embedded system, and program to satisfy given user specifications.		K3
CO 4	Use commercial tools to develop Arm-based embedded systems.		K3
CO 5	Use commercial API and tools to accelerate the development cycle of Arm-based embedded sys	stems	К3

Course Code	BEC0512P	LTP	Credits
<b>Course Title</b>	AI & ML Lab	004	2
<b>Course Objectiv</b>	es: The student will learn about	Bloom	Level
1	Implement the blind search algorithm.	K3	l.
2	Implement the different AI based problem	K3	l.
3	Apply various chaining algorithm in AI using python/Open CV	K4	
4	Apply appropriate data sets to the Machine Learning algorithms.	K4	
5	Identify and apply Machine Learning algorithms to solve real world problems.	K5	
Pre-requisites: B			
•	List of Experiments		
S.No	Name of Experiment		CO
1	Implementation of Python basic Libraries such as Math, Numpy and Scipy.		CO1
2	Implementation of Python Libraries for ML application such as Pandas and Matplotlib.		CO1
3	Creation and Loading different datasets in Python.		CO1
4	Familiarizing with Anaconda for importing modules and dependencies for ML.		CO1
5	Familiarizing with Jupyter for importing Modules and dependencies for ML.		CO1
6	Write a python program to compute Mean, Median.		CO1
7	Write a python program to compute Mode, Variance and Standard Deviation using Datasets.		CO1
8	Write a Program to Implement Breadth First Search using Python.		CO1
9	Write a Program to Implement Depth First Search using Python.		CO1
10	Write a program to implement Hill Climbing Algorithm using Python.		CO2
11	Write a program to implement Tic-Tac-Toe Game using Python.		CO2
12	Write a Program to implement Game Playing Algorithms: Minimax.		CO2
13	Write a Program to Implement A* Algorithm using Python.		CO2
14	Write a Program to implement Game Playing Algorithms: Alpha Beta Pruning.		CO2
15	Write a Program to implement Chatbot in Python.		CO2
16	Write a Program to Implement Missionaries Cannibals Problems using Python.		CO2
17	Write a Program to Implement 8-Puzzle Problem using Python.		CO2
18	Write a program to solve water jug problem using Python.		CO2
19	Write a program to solve Monkey banana problem using Python.		CO2
20	Write a program to Implement N-Queens Problem Using Python.		CO2
21	Write a program to Implement of Traveling Salesman using Python.		CO2
22	Write a Program to Implement Tower of Hanoi using Python.		CO2
23	Write a Program to Implement Forward Chaining.		CO3
24	Write a Program to Implement Backward Chaining		CO3

25	Implement the S algorithm for finding the most specific hypothesis based on a given set of training data samples.	CO4
	Read the training data from a .csv file.	
26	For a given set of training data examples stored in a .csv file, implement and demonstrate the Candidate-	CO4
	Elimination algorithm to output a description of the set of all hypotheses consistent with the training examples.	
27	Build an Artificial Neural Network by implementing the Back propagation algorithm and test the same using	CO4
	appropriate data sets.	
28	Implement the non-parametric Locally Weighted Regression algorithm in order to fit data points. Select	CO4
	appropriate data set for your experiment and draw graphs.	
29	Implement the S algorithm for finding the most specific hypothesis based on a given set of training data samples.	CO4
	Read the training data from a .csv file.	
30	Write a program to implement the naïve Bayesian classifier for a sample training data set stored as a .csv file.	CO5
	Compute the accuracy of the classifier, considering few test data sets.	
31	Write a program to construct a Bayesian network considering medical data. Use this model to demonstrate the	CO5
	diagnosis of heart patients using standard Heart Disease Data Set. You can use Java/Python ML library	
	classes/API.	
32	Apply EM algorithm to cluster a set of data stored in a .csv file. Use the same data set for clustering using k-	CO5
	Means algorithm. Compare the results of these two algorithms and comment on the quality of clustering. You	
	can add Java/Python ML library classes/API in the program.	
33	Write a program to implement k-Nearest Neighbor algorithm to classify the iris data set. Print both correct and	CO5
	wrong predictions. Java/Python ML library classes can be used for this problem.	
34	Write a program to demonstrate the working of the decision tree based ID3 algorithm. Use an appropriate data	CO5
	set for building the decision tree and apply this knowledge to classify a new sample.	
<b>Course Outcome:</b>	After successful completion of this Lab students will be able to	Blooms
		Level
CO 1	Implement the blind search algorithm.	K3
CO 2	Implement the different AI based problem	K3
CO 3	Apply various chaining algorithm in AI using python/Open CV	K4
CO 4	Apply appropriate data sets to the Machine Learning algorithms.	K4
CO 5	Identify and apply Machine Learning algorithms to solve real world problems.	K5
	1 11 7 0 0	

	Bachelor of Technology Third Year	•
Course Code	BNC0501 L T P	Credits
<b>Course Title</b>	Constitution of India 200	NC
Course Objective	es: The student will learn about	
1	Learn the legacies of constitutional development in India and understand the most diversified legal document	K1, K2
	of India and philosophy behind it.	
2	Aware of the theoretical and functional aspects of the Indian Parliamentary System.	K1
3	Understand the legal concepts and its implications for engineers.	K2
4	Learn the law of intellectual property rights.	K1
5	Learn the role of engineering in business organizations and e-governance.	K1
Pre-requisites: Po	olitical science	
	Course Contents / Syllabus	
UNIT-I	Introduction and Basic Information about Indian Constitution	6 hours
Meaning of the co	onstitution law and constitutionalism, Historical Background of the Constituent Assembly, Government of India A	ct of 1935 an
<u> </u>	nce Act of 1947, Enforcement of the Constitution, Indian Constitution and its Salient Features, The Preamble of th	
	nce Act of 1747, Emolecinent of the Constitution, mutan Constitution and its Sanent Features, The Freamole of th	t Constitution
Fundamental Righ	hts, Fundamental Duties, Directive Principles of State Policy, Parliamentary System, Federal System, Centre- S	tate Relations
Fundamental Righ Amendment of the		tate Relations ia, Emergenc
Fundamental Righ Amendment of the Provisions: Nation	hts, Fundamental Duties, Directive Principles of State Policy, Parliamentary System, Federal System, Centre-S ne Constitutional Powers and Procedure, The historical perspectives of the constitutional amendments in Ind	tate Relations ia, Emergenc
Fundamental Righ Amendment of the Provisions: Nation UNIT-II	hts, Fundamental Duties, Directive Principles of State Policy, Parliamentary System, Federal System, Centre-Sene Constitutional Powers and Procedure, The historical perspectives of the constitutional amendments in Indial Emergency, President Rule, Financial Emergency, and Local Self Government – Constitutional Scheme in Indial Union Executive and State Executive	tate Relations ia, Emergenc a. 6 hours
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Sole Traders, Partnerships: Companies: The Company's Act: Introduction, Formation of a Company, Memorandum of Association, Articles of Association, Prospectus, Shares, Directors, General Meetings and Proceedings, Auditor, Winding up.

E-Governance and role of engineers in E-Governance, Need for reformed engineering serving at the Union and State level, Role of I.T. professionals in Judiciary, Problem of Alienation and Secessionism in few states creating hurdles in Industrial development.

	Course Outcomes	s: At the end of this course students will demonstrate the ability to
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CO 1	Identify and explore the basic features and modalities about Indian constitution.	K1
CO 2	Differentiate and relate the functioning of Indian parliamentary system at the center and state level.	K2, K3
CO 3	Differentiate different aspects of Indian Legal System and its related bodies.	K2
CO 4	Discover and apply different laws and regulations related to engineering practices.	К3
CO 5	Correlate role of engineers with different organizations and governance models	K4

#### Text books:

- 1. M Laxmikanth: Indian Polity for civil services and other State Examination,6th Edition, Mc Graw Hill.
- 2. Brij Kishore Sharma: Introduction to the Indian Constitution, 8th Edition, PHI Learning Pvt. Ltd.
- 3. Prabudh Ganguli: Gearing up for Patents: The Indian Scenario, Orient Longman.

#### **Reference Books:**

- 1. BL Wadehra: Patents, Trademarks, Designs and Geological Indication Universal Law Publishing LexisNexis.
- 2. Executive programme study material Company Law, Module II, by ICSI (The Institute of Companies Secretaries of India) (Only relevant sections i.e., Study 1, 4 and https://www.icsi.edu/media/webmodules/publications/Company%20Law.pdf
- 3. Handbook on e-Governance Project Lifecycle, Department of Electronics & Information Technology, Government of India, https://www.meity.gov.in/writereaddata/files/eGovernance Project\_Lifecycle\_Participant\_Handbook-5Day\_CourseV1\_20412.pdf

## Links:

Unit 1	https://legalaffairs.nalsar.ac.in/students/student/course-details/1
Unit 2	https://www.youtube.com/watch?v=lZ2tvimrLRQ&t=281s
Unit 3	https://www.youtube.com/watch?v=H0_olSSX6D8&t=2s
Unit 4	https://www.youtube.com/watch?v=WvduZOWoft0
Unit 5	https://www.youtube.com/watch?v=7SmrFh88Cuk

	Bachelor of Technology Third Year		
Course Code	BNC0502 L 7	' <b>P</b>	Credits
Course Title	Essence of Indian Traditional Knowledge 2 (	0	NC
<b>Course Objectives</b>	s: The student will learn about		
	to provide basic knowledge about different theories of society, state and polity in India, Indian literature	, cultu	re, Indian
	y, science, management, cultural heritage and different arts in India.		
Pre-requisites: Ba	sic science and Indian Culture		
	Course Contents / Syllabus		
UNIT-I	Society State and Polity in India		6 hours
, Council of Ministerin Ancient India, Frepresentation of W	dia: Evolutionary Theory, Force Theory, Mystical Theory Contract Theory, Stages of State Formation in An ers Administration Political Ideals in Ancient India Conditions' of the Welfare of Societies, The Seven Limbsurus Thank Varnāshrama System, Āshrama or the Stages of Life, Marriage, Understanding Gender as a Women in Historical traditions, Challenges faced by Women.	of the	State, Society category, The
UNIT-II	Indian Literature, Culture, Tradition and Practices		6 hours
	and languages in India: Harappan Script and Brahmi Script. The Vedas, the Upanishads, the Ramayana a		
Puranas, Buddhist Literature, Kannad Literature	And Jain Literature in Pali, Prakrit And Sanskrit, Sikh Literature, Kautilya's Arthashastra, Famous Sans la Literature, Malayalam Literature, Sangama Literature Northern Indian Languages & Literature, Persi	krit Au	thors, Telugu l Urdu ,Hindi
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# **Text books:**

- 1. Sivaramakrishna (Ed.), Cultural Heritage of India-Course Material, Bharatiya Vidya Bhavan, Mumbai, 5th Edition, 2014.
- 2. S. Baliyan, Indian Art and Culture, Oxford University Press, India
- 3. Nitin Singhania, Indian Art and Culture: for civil services and other competitive Examinations,3rd Edition,Mc Graw Hill

# **Reference Books:**

- 1. Romila Thapar, Readings In Early Indian History Oxford University Press, India
- 2. Basham, A.L., The Wonder that was India (34th impression), New Delhi, Rupa & co.

	Bachelor of Technology Third Year		
Course Code	BEC0601	LTP	Credits
Course Title	5G Technology	310	4
0 01 4			

#### **Course Objectives: The student will learn about**

Student will get in-depth understanding of the 5G technology, focusing on its architecture, design principles, and core capabilities. Topics include 5G network components, network slicing, edge computing, and the transition from 4G LTE. Students will explore enabling technologies like massive MIMO, beamforming, and millimeter-wave communication. The course also covers protocols, spectrum management, and latency reduction. Emphasis is placed on real-world applications such as IoT, smart cities, and Industry 4.0, along with 5G security, regulatory aspects, and integration with AI and cloud platforms.

**Pre-requisites:** A basic understanding of wireless communication, 4G Technology and networking concepts.

# **Course Contents / Syllabus**

UNIT-I Introduction to 5G Architecture and Protocols

Introduction to 5G RAN (Radio Access Networks), 5G NR Logical architectures, 5G NR Protocol stack (Layer 2 and Layer 3)

**Introduction to Physical Layer:** Physical layer techniques, 5G NR MAC layer Architecture, functions, Channel Mapping, Procedures, Headers and Subheaders.

## UNIT-II Propagation Scenarios and Channel Modelling

8 hours

8 hours

Channel modelling requirements, propagation scenarios and challenges in the 5G modelling, Channel Models for mm Wave MIMO Systems. 5G Requirements, Key Capabilities of 5G versus 4G, 5G operating scenario, mm wave technology, Propagation modelling of 5G. The architecture and function of core network nodes in 5G. Components and protocols involved in the 5G core.

## UNIT-III Massive MIMO Techniques

8 hours

Massive MIMO propagation channel models, Channel Estimation in Massive MIMO, Massive MIMO with Imperfect CSI, Multi-Cell Massive MIMO. Compare legacy (4G LTE) and modern (5G) core architectures. Configuration of 5G CN elements. Beamforming.

# UNIT-IV Mobility and Handoff Management

8 hours

Interference and mobility management in 5G, Handoff management in 5G, QoS improvement with 5G, QoS mechanisms offered by 5G, 5G QoS Flow Descriptions and Characteristics. IP Routing: Types of routing protocols, IPv6 addressing.

### UNIT-V Network Slicing and Function Virtualization

8 hours

Network Slicing: Concept, architecture, the status of network slicing in 5G standards, network slicing in core networks, network slicing challenges for 5G Networks. Network Functions Virtualization (NFV): Functionality, architecture, advantages for 5G network.

CO 1	Demonstrate Radio access network and protocol stack.	K1, K2
CO 2	Analyze indoor and outdoor propagation models.	K1, K2
CO 3	Apply massive MIMO technique in wireless communication.	K2
CO 4	Apply mobility management in heterogeneous and network-controlled handover.	K1, K2
CO 5	Demonstrate the fundamentals of network slicing core networks.	K1, K2, K3

#### **Text books:**

- 1. Martin Sauter "From GSM to LTE-Advanced Pro and 5G: An Introduction to Mobile Networks and MobileBroadband", Wiley-Blackwell, 2017.
- 2. Afif Osseiran, Jose. F. Monserrat, Patrick Marsch, "Fundamentals of 5G Mobile Networks", Cambridge University Press. Radar Principles, Technology, Applications, Byron Edde, Pearson Education, 2004.
- 3. Athanasios G.Kanatos, Konstantina S.Nikita, Panagiotis Mathiopoulos, "New Directions in Wireless Communications Systems From Mobile to 5G", Taylor & Francis, 2018,

## **Reference Books:**

- 1. Jonathan Rodriguez, "Fundamentals of 5G Mobile Networks", John Wiley &Sons.WHHayt and JA Buck, "Engineering Electromagnetic", 7th Edition TMH, 2013.
- 2. Theodore S.Rappaport, Robert W.Heath, Robert C.Danials, James N.Murdock "Millimeter Wave Wireless Communications", Prentice Hall Communications.

# NPTEL/ YouTube/ Faculty Video Link:

Unit I	https://www.youtube.com/watch?v=aYJncUscfmk
Unit II	https://www.youtube.com/watch?v=khsqASfv2T4&list=PLxJYaXA6j4AbpWZmDztACJNA5vA3rvfM0&index=6
Unit III	https://www.youtube.com/watch?v=am3Zs8QpLLY
Unit IV	https://www.youtube.com/watch?v=q9Pk68iAHVA
Unit V	https://www.youtube.com/watch?v=pUlfcGyFCFo

Bachelor of Technology Third Year				
Course Code	BEC0611	LTP	Credits	
Course Title	Control System and Automation	300	3	

Course Objectives: The student will learn about

The student will learn about the basics of control systems along with analysis of time domain response & concepts of absolute and relative stability for continuous data systems. Also, the concept of state space analysis in a control system & introduction to robotics automation.

**Pre-requisites:** Basic knowledge of differential equations, signals and systems, linear algebra, and fundamental electrical engineering concepts.

# **Course Contents / Syllabus**

# UNIT-I Basic of a Control System 8 hours

Transfer function, Basic of a control system, Introduction: open-loop control system, close-loop control system, Block diagram, Signal flow graph, Modelling a control system: Electrical network, Mechanical system, Servo motor. Transient and steady state response, Input test signal, Time response of a first order control system, Time response of a second order control system, steady state Error, Design of controller.

## UNIT-II Concept of Stability

8 hours

Stability in terms of characteristic equation, Routh Hurwitz criterion, Root-Locus Technique, Frequency domain analysis of control system, Nyquist stability criterion, stability analysis with the Bode plot, relative stability, Compensation of control system.

### **UNIT-III** State Space Representation

8 hours

State space representation, the concept of state, Block diagram for a state equation, Transfer function decomposition, Solution of state equation, Transfer matrix, Controllability, and Observability. Transfer function of discrete data system, State equations of linear discrete data system, State error analysis of discrete data control system.

#### UNIT-IV Introduction to Robot

8 hours

Introduction to Robot: Classification of Robots, Advantages and Disadvantages of Robots, Robot Components, Robot Degrees of Freedom, Robot Joints, Robot Coordinates, Robot Reference Frames, Programming Modes, Robot Characteristics, Robot Workspace, Robot Languages. Introduction to RPA.

#### UNIT-V Introduction to Automation

8 hours

Introduction to Automation: Definition and fundamentals of automation, reasons for Automating, Electro pneumatics: Electro pneumatics, Design of Electro-Pneumatic Circuits, PLC- Architecture, PLC Programming Languages, ladder digs, Ladder Logic, Programming for different types of logic: Timers, Counter. Practical Examples of Ladder Programming.

CO 1	Describe the basics of control system with time domain specifications.	K2
CO 2	Explain the concepts of absolute and relative stability for continuous data systems and designing of	K4
	compensator.	
CO 3	Analyse the control system design in state space & describe the discrete data control system.	K4
CO 4	Explain the role control system in robotic	K2
CO 5	Analysis of electro pneumatics hydraulics & discrete control using PLC.	К3
Text books:	·	
1. B.	C. Kuo & Farid GolNaraghi, "Automatic Control Systems", 9th Edition, John Wiley India,2008.	
2. Sa	eed B. Niku, "Introduction to Robotics – Analysis, Systems and Application": PHI 2006.	
Reference Boo		
1. "A	utomation, Production Systems and Computer Integrated Manufacturing"- M.P. Grover, Pearson Education.	
2. Ar	n Introduction to Automated Process Planning Systems" – Tiess Chiu Chang & Richard A. Wysk.	
NPTEL/ You	Гube/ Faculty Video Link:	
Unit I	https://onlinecourses.nptel.ac.in/noc20_ee90/preview	
Unit II	https://onlinecourses.nptel.ac.in/noc21_me49/preview	
Unit III	https://www.youtube.com/watch?v=P_PP76flZfw&list=PLyqSpQzTE6M_XM9cvjLLO_Azt1FkgPhpH&index=2	
Unit IV	https://youtu.be/pSEjWxqE3R0	
Unit V	https://onlinecourses.nptel.ac.in/noc20_ee90/preview	

Course Code	BEC0614 LTP	Credits
<b>Course Title</b>	Robotics Design Mechanism 3 0 0	3
<b>Course Objective</b>	es: The student will learn about	
1	Industrial robots and their operational workspace characteristics & the tools taking part in the manufacturing	K2
	process.	
2	Dynamic analysis of drives.	K4
3	The feedback sensors its types & transporting devices.	K2
4	The feeding materials used according to application & orientation.	K3
5	Functional systems & prototypes of robots.	K2, K3
<b>Pre-requisites:</b> B	asics of mathematics and python programming	
	Course Contents / Syllabus	
UNIT-I	Review and Definitions	8 hours
01111-1	Review and Definitions	
	ds, Definition of Levels, Manipulators, Structure of Automatic Industrial Systems, Non-industrial Representative	s of the Robo
Robots & its Kin		s of the Robo
Robots & its Kin Family, Relations	ds, Definition of Levels, Manipulators, Structure of Automatic Industrial Systems, Non-industrial Representative	
Robots & its King Family, Relations Concepts and La Kinematic Layout	ds, Definition of Levels, Manipulators, Structure of Automatic Industrial Systems, Non-industrial Representative hip between the Level of Robot "Intelligence" and the Product. <b>ayouts:</b> Processing Layout, Concept of an Automatic Manufacturing Process, Productivity of a Manufacturing t, Rapid Prototyping.	Process, Then
Robots & its Kin- Family, Relations Concepts and La	ds, Definition of Levels, Manipulators, Structure of Automatic Industrial Systems, Non-industrial Representative hip between the Level of Robot "Intelligence" and the Product.  ayouts: Processing Layout, Concept of an Automatic Manufacturing Process, Productivity of a Manufacturing	
Robots & its King Family, Relations Concepts and La Kinematic Layout UNIT-II Electromagnetic I	ds, Definition of Levels, Manipulators, Structure of Automatic Industrial Systems, Non-industrial Representative hip between the Level of Robot "Intelligence" and the Product.  ayouts: Processing Layout, Concept of an Automatic Manufacturing Process, Productivity of a Manufacturing t, Rapid Prototyping.  Kinematics and Control of Automatic Machines  Drive, Electric Drives, Hydraulic Drive, Pneumo-drive, Brakes, Drive with a Variable Moment of Inertia.	Process, Ther  8 hours
Robots & its King Family, Relations Concepts and La Kinematic Layout UNIT-II Electromagnetic I Kinematics and	ds, Definition of Levels, Manipulators, Structure of Automatic Industrial Systems, Non-industrial Representative hip between the Level of Robot "Intelligence" and the Product.  ayouts: Processing Layout, Concept of an Automatic Manufacturing Process, Productivity of a Manufacturing t, Rapid Prototyping.  Kinematics and Control of Automatic Machines  Drive, Electric Drives, Hydraulic Drive, Pneumo-drive, Brakes, Drive with a Variable Moment of Inertia.  Control of Automatic Machines: Position Function, Camshafts, Master Controller, Amplifiers, Dynamic Accuracy	Process, Ther  8 hours
Robots & its King Family, Relations Concepts and La Kinematic Layout UNIT-II Electromagnetic I Kinematics and G Harmful Vibration	ds, Definition of Levels, Manipulators, Structure of Automatic Industrial Systems, Non-industrial Representative hip between the Level of Robot "Intelligence" and the Product.  ayouts: Processing Layout, Concept of an Automatic Manufacturing Process, Productivity of a Manufacturing t, Rapid Prototyping.  Kinematics and Control of Automatic Machines  Drive, Electric Drives, Hydraulic Drive, Pneumo-drive, Brakes, Drive with a Variable Moment of Inertia.  Control of Automatic Machines: Position Function, Camshafts, Master Controller, Amplifiers, Dynamic Accuracy, Automatic Vibration Damping, Electrically Controlled Vibration Dampers.	Process, Ther  8 hours  y, Damping of
Robots & its King Family, Relations Concepts and La Kinematic Layout UNIT-II Electromagnetic I Kinematics and	ds, Definition of Levels, Manipulators, Structure of Automatic Industrial Systems, Non-industrial Representative hip between the Level of Robot "Intelligence" and the Product.  ayouts: Processing Layout, Concept of an Automatic Manufacturing Process, Productivity of a Manufacturing t, Rapid Prototyping.  Kinematics and Control of Automatic Machines  Drive, Electric Drives, Hydraulic Drive, Pneumo-drive, Brakes, Drive with a Variable Moment of Inertia.  Control of Automatic Machines: Position Function, Camshafts, Master Controller, Amplifiers, Dynamic Accuracy	Process, Ther  8 hours
Robots & its King Family, Relations Concepts and La Kinematic Layout UNIT-II Electromagnetic I Kinematics and Harmful Vibration UNIT-III Linear and Angul	ds, Definition of Levels, Manipulators, Structure of Automatic Industrial Systems, Non-industrial Representative hip between the Level of Robot "Intelligence" and the Product.  ayouts: Processing Layout, Concept of an Automatic Manufacturing Process, Productivity of a Manufacturing to the Rapid Prototyping.  Kinematics and Control of Automatic Machines  Drive, Electric Drives, Hydraulic Drive, Pneumo-drive, Brakes, Drive with a Variable Moment of Inertia.  Control of Automatic Machines: Position Function, Camshafts, Master Controller, Amplifiers, Dynamic Accurace and Automatic Vibration Damping, Electrically Controlled Vibration Dampers.  Transporting Devices  ar Displacement Sensors, Speed and Flow-Rate Sensors, Force Sensors Temperature Sensors, Item Presence Sensors	Process, Ther  8 hours  y, Damping of  8 hours
Robots & its King Family, Relations Concepts and La Kinematic Layout UNIT-II Electromagnetic I Kinematics and Harmful Vibration UNIT-III Linear and Angul Transporting De	ds, Definition of Levels, Manipulators, Structure of Automatic Industrial Systems, Non-industrial Representative hip between the Level of Robot "Intelligence" and the Product.  ayouts: Processing Layout, Concept of an Automatic Manufacturing Process, Productivity of a Manufacturing t, Rapid Prototyping.  Kinematics and Control of Automatic Machines  Drive, Electric Drives, Hydraulic Drive, Pneumo-drive, Brakes, Drive with a Variable Moment of Inertia.  Control of Automatic Machines: Position Function, Camshafts, Master Controller, Amplifiers, Dynamic Accuracy, Automatic Vibration Damping, Electrically Controlled Vibration Dampers.  Transporting Devices	Process, Ther  8 hours  y, Damping of  8 hours
Robots & its King Family, Relations Concepts and La Kinematic Layout UNIT-II Electromagnetic I Kinematics and Harmful Vibration UNIT-III Linear and Angul	ds, Definition of Levels, Manipulators, Structure of Automatic Industrial Systems, Non-industrial Representative hip between the Level of Robot "Intelligence" and the Product.  ayouts: Processing Layout, Concept of an Automatic Manufacturing Process, Productivity of a Manufacturing to the Rapid Prototyping.  Kinematics and Control of Automatic Machines  Drive, Electric Drives, Hydraulic Drive, Pneumo-drive, Brakes, Drive with a Variable Moment of Inertia.  Control of Automatic Machines: Position Function, Camshafts, Master Controller, Amplifiers, Dynamic Accurace and Automatic Vibration Damping, Electrically Controlled Vibration Dampers.  Transporting Devices  ar Displacement Sensors, Speed and Flow-Rate Sensors, Force Sensors Temperature Sensors, Item Presence Sensors	Process, Ther  8 hours  y, Damping of  8 hours
Robots & its King Family, Relations Concepts and Lakinematic Layour UNIT-II Electromagnetic I Kinematics and Harmful Vibration UNIT-III Linear and Angul Transporting Defunit-IV	ds, Definition of Levels, Manipulators, Structure of Automatic Industrial Systems, Non-industrial Representative hip between the Level of Robot "Intelligence" and the Product.  ayouts: Processing Layout, Concept of an Automatic Manufacturing Process, Productivity of a Manufacturing t, Rapid Prototyping.  Kinematics and Control of Automatic Machines  Drive, Electric Drives, Hydraulic Drive, Pneumo-drive, Brakes, Drive with a Variable Moment of Inertia.  Control of Automatic Machines: Position Function, Camshafts, Master Controller, Amplifiers, Dynamic Accuraces, Automatic Vibration Damping, Electrically Controlled Vibration Dampers.  Transporting Devices  ar Displacement Sensors, Speed and Flow-Rate Sensors, Force Sensors Temperature Sensors, Item Presence Sensors Temperature Sensors Sensors Temperature Sensors Sens	Process, Ther  8 hours  y, Damping or  8 hours  rs.
Robots & its King Family, Relations Concepts and La Kinematic Layout UNIT-II Electromagnetic I Kinematics and Harmful Vibration UNIT-III Linear and Angul Transporting De UNIT-IV Introduction, Fee	ds, Definition of Levels, Manipulators, Structure of Automatic Industrial Systems, Non-industrial Representative hip between the Level of Robot "Intelligence" and the Product.  ayouts: Processing Layout, Concept of an Automatic Manufacturing Process, Productivity of a Manufacturing t, Rapid Prototyping.  Kinematics and Control of Automatic Machines  Drive, Electric Drives, Hydraulic Drive, Pneumo-drive, Brakes, Drive with a Variable Moment of Inertia.  Control of Automatic Machines: Position Function, Camshafts, Master Controller, Amplifiers, Dynamic Accurace as, Automatic Vibration Damping, Electrically Controlled Vibration Dampers.  Transporting Devices  ar Displacement Sensors, Speed and Flow-Rate Sensors, Force Sensors Temperature Sensors, Item Presence Sensor Vices: General Considerations, Linear Transportation, Rotational Transportation, Vibrational Transportation  Types of Orientation	Process, Ther  8 hours  y, Damping of  8 hours  rs.  8 hours  m Magazines
Robots & its King Family, Relations Concepts and La Kinematic Layout UNIT-II Electromagnetic I Kinematics and Harmful Vibration UNIT-III Linear and Angul Transporting De UNIT-IV Introduction, Fee	ds, Definition of Levels, Manipulators, Structure of Automatic Industrial Systems, Non-industrial Representative hip between the Level of Robot "Intelligence" and the Product.  ayouts: Processing Layout, Concept of an Automatic Manufacturing Process, Productivity of a Manufacturing to Rapid Prototyping.  Kinematics and Control of Automatic Machines  Drive, Electric Drives, Hydraulic Drive, Pneumo-drive, Brakes, Drive with a Variable Moment of Inertia.  Control of Automatic Machines: Position Function, Camshafts, Master Controller, Amplifiers, Dynamic Accuraces, Automatic Vibration Damping, Electrically Controlled Vibration Dampers.  Transporting Devices  ar Displacement Sensors, Speed and Flow-Rate Sensors, Force Sensors Temperature Sensors, Item Presence Sensor vices: General Considerations, Linear Transportation, Rotational Transportation, Vibrational Transportation  Types of Orientation  ding of Liquid and Granular Materials, Feeding of Strips, Rods, Wires, Ribbons, Feeding of Oriented Parts from Bins, General Discussion of Orientation of Parts, Passive Orientation, Active Orientation, Logical Orientation	Process, Ther  8 hours  y, Damping of  8 hours  rs.  8 hours  m Magazines
Robots & its King Family, Relations Concepts and Lagour UNIT-II Electromagnetic I Kinematics and Harmful Vibration UNIT-III Linear and Angul Transporting De UNIT-IV Introduction, Fee Feeding of Parts by Non-mechanic UNIT-V	ds, Definition of Levels, Manipulators, Structure of Automatic Industrial Systems, Non-industrial Representative hip between the Level of Robot "Intelligence" and the Product.  ayouts: Processing Layout, Concept of an Automatic Manufacturing Process, Productivity of a Manufacturing t, Rapid Prototyping.  Kinematics and Control of Automatic Machines  Drive, Electric Drives, Hydraulic Drive, Pneumo-drive, Brakes, Drive with a Variable Moment of Inertia.  Control of Automatic Machines: Position Function, Camshafts, Master Controller, Amplifiers, Dynamic Accurace instance Automatic Vibration Damping, Electrically Controlled Vibration Dampers.  Transporting Devices  are Displacement Sensors, Speed and Flow-Rate Sensors, Force Sensors Temperature Sensors, Item Presence Sensor vices: General Considerations, Linear Transportation, Rotational Transportation, Vibrational Transportation  Types of Orientation  ding of Liquid and Granular Materials, Feeding of Strips, Rods, Wires, Ribbons, Feeding of Oriented Parts froffrom Bins, General Discussion of Orientation of Parts, Passive Orientation, Active Orientation, Logical Orientatical Means.  Manipulators	Process, Ther  8 hours  y, Damping of  8 hours  rs.  8 hours  m Magazines
Robots & its King-Family, Relations Concepts and Laguer Kinematic Layour UNIT-II Electromagnetic I Kinematics and Harmful Vibration UNIT-III Linear and Angul Transporting Defunitarion of Parts in by Non-mechanic UNIT-V General Concepts	ds, Definition of Levels, Manipulators, Structure of Automatic Industrial Systems, Non-industrial Representative hip between the Level of Robot "Intelligence" and the Product.  ayouts: Processing Layout, Concept of an Automatic Manufacturing Process, Productivity of a Manufacturing to Rapid Prototyping.  Kinematics and Control of Automatic Machines  Drive, Electric Drives, Hydraulic Drive, Pneumo-drive, Brakes, Drive with a Variable Moment of Inertia.  Control of Automatic Machines: Position Function, Camshafts, Master Controller, Amplifiers, Dynamic Accuraces, Automatic Vibration Damping, Electrically Controlled Vibration Dampers.  Transporting Devices  ar Displacement Sensors, Speed and Flow-Rate Sensors, Force Sensors Temperature Sensors, Item Presence Sensor vices: General Considerations, Linear Transportation, Rotational Transportation, Vibrational Transportation  Types of Orientation  ding of Liquid and Granular Materials, Feeding of Strips, Rods, Wires, Ribbons, Feeding of Oriented Parts from Bins, General Discussion of Orientation of Parts, Passive Orientation, Active Orientation, Logical Orientatical Means.	Process, Ther  8 hours  y, Damping or  8 hours  rs.  8 hours  m Magazines on, Orientation

CO 1	Explain industrial robots and their operational workspace characteristics & Manipulators.	K1, K2
CO 2	Analyze drives & its control.	K2
CO 3	Describe the use of sensors & solve kinematics of robot manipulators.	K3
CO 4	Apply feed material & orientation.	K4, K5
CO 5	Create application-based prototypes of robots.	K1, K3
Text books:	·	<b>-</b>
1. Bo	n-Zion Sandler: Robotics designing the mechanisms for automated machinery, Prentice-Hall.	
2. Pe	ssen, D. W.: Industrial Automation, John Wiley & Sons, New York.	
Reference Bo	oks:	
1. So	hey, John A., Introduction to Manufacturing Processes: Second Edition, McGraw-Hill International.	
2. C1	itchlow, Arthur J., Introduction to Robotics, Macmillan Publishing Company, New York, Collier Macmillan Publisl	ners, Londo
NPTEL/ You	Гube/ Faculty Video Link:	
Unit I	https://onlinecourses.nptel.ac.in/noc20_ee90/preview	
Unit II	https://onlinecourses.nptel.ac.in/noc21_me49/preview	
Unit III	https://www.youtube.com/watch?v=P_PP76flZfw&list=PLyqSpQzTE6M_XM9cvjLLO_Azt1FkgPhpH&index=2	2
Unit IV	https://youtu.be/pSEjWxqE3R0	
Unit V	https://onlinecourses.nptel.ac.in/noc20_ee90/preview	

	Bachelor of Technology Third Year		
<b>Course Code</b>	BEC0612	LTP	Credits
<b>Course Title</b>	Image Processing and Pattern Recognition	300	3
<b>Course Objective</b>	es: The student will learn about		
1	Basics of digital image and various operations on it.		K1, K2
2	Image enhancement techniques in different domains.		K1, K2
3	The various noises in images and restoration methods.		K1, K2
4	Skills to segment a digital image with different methods.		K1, K2
5	The basics of colour image processing and various image compression techniques.		K1, K2
<b>Pre-requisites:</b> B	asic fundamental of mathematics and signal processing		
	Course Contents / Syllabus		
UNIT-I	Introduction to Digital Image Processing		8 hours
	cessing: Definition, Basic image file formats, Fundamental Steps in Digital Image Processing		
	n, Image Sensing and Acquisition, Image Sampling and Quantization, Basic Relationship be	tween Pixels, Applica	tions of DIP.
UNIT-II	Image Enhancement Techniques		8 hours
	Basic Gray Level Transformations, Histogram based Processing, Enhancement using A	Arithmetic/Logic Open	rations, Spati
_	ing and Sharpening Filter.		
	in: Image Smoothing and Image Sharpening Using Frequency Domain Filters, Homomorph	nic Filtering.	
UNIT-III	Image Restoration Model		8 hours
mage Degradation	Restoration process model, Noise Models, Restoration in the presence of noise only spatial	filtering, Periodic noi	se reduction b
Frequency domain	filtering.		
Compression: Loss	sless compression: Variable length coding, LZW coding, Bit plane coding, Predictive	coding-DPCM, Lossy	Compressio
Γransform coding,	Wavelet coding, Basics of Image compression standards: JPEG, MPEG		
UNIT-IV	Image Segmentation		8 hours
Point, Line and Ed	dge Detection, Thresholding: Otsu and Adaptive, Region-Based Segmentation, Segmentatio	n: Morphological Wat	ershed, K-
	C-means, Wavelet transform, Discrete wavelet transform, Hough transform.	1 0	,
UNIT-V	Color Image Processing		8 hours
Fundamentals of d	lifferent colour models - RGB, CMY, HSI, YCbCr, Lab; False colour; Pseudo colour; Enhar	cement; Segmentation	n. Dilation an

СО	Apply knowledge of mathematics for image understanding and analysis.	K1, K3
CO	Analyse various image enhancement techniques in different domains.	K3, K4
CO	Recognize various noises in images and apply restoration methods.	K3, K4
CO	4 Apply different segmentation techniques on image.	K3
CO	Apply knowledge of mathematics for image understanding and analysis.	K1, K3
Text books:		•
1.	Rafael C. Gonzalez, Richard E. Woods, Digital Image Processing Pearson, Third Edition, 2010.", Prentice Hall of Indiana.	lia.
2.	Anil K. Jain, Fundamentals of Digital Image Processing Pearson, 2002.	
Reference Bo	ooks:	
1. N	Milan Sonka, Vaclav Hlavav, Roger Boyle, —Image Processing, Analysis and Machine Vision, 2nd ed., Thomson Lear	ning, 2001.
2. R	Rangaraj M. Rangayyan, —Biomedical Image Analysis , CRC Press, 2005	
3. P	ratt W.K, —Digital Image Processing, 3rd ed., John Wiley & Sons, 2007	
4. E	Digital Image Processing, 3rd Edition, by Rafael C Gonzalez and Richard E Woods. Publisher: Pearson Education	
NPTEL/ You	uTube/ Faculty Video Link:	
Unit I	https://youtu.be/T0bgf3V7u-E	
Unit II	https://youtu.be/bJjgyTQ-BT4	
	https://youtu.be/M7JxDHUW5cc	
	https://youtu.be/JfrcMYBouJE	
Unit III	https://youtu.be/MrNafUqh860	
	https://youtu.be/gLTlQPYY_pw	
Unit IV	https://youtu.be/j3_Ck5oP5oI	
	https://youtu.be/q1J0VAYFkHg	
Unit V	https://youtu.be/kSzramCsHA4	
	https://youtu.be/nlwH07G9Efg	

	Bachelor of Technology Third Year			
Course Code	BEC0615	LTP	Credits	
Course Title	ANN & Deep Learning	300	3	
<b>Course Objectives:</b>	The student will learn about			
	out the basic principles and techniques of artificial neural network and deep learning, PCA, auto eso learn how to critically evaluate model performance and interpret results.	encoders, CNN	I, RNN, GRU	
Pre-requisites: Wor	king knowledge of Linear Algebra, Probability Theory. It would be beneficial if the participants hav	e done a cours	se on Machine	
Learning.				
	Course Contents / Syllabus			
UNIT-I	Introduction to Deep Learning		8 hours	
Introduction: History	of Deep Learning, Deep Learning Success Stories, McCulloch Pitts Neuron, ANN and its typ	es, Multilayer	Perceptron's	
(MLPs), Representation	on Power of MLPs, Sigmoid Neurons, RELU activation, Gradient Descent, Activation Functions, Lo	oss Functions,	Feed Forward	
Neural Networks, Bac	Neural Networks, Back propagation.			
UNIT-II	Principal Component Analysis		8 hours	
Gradient Descent (GD), Momentum Based GD, Nesterov Accelerated GD, Stochastic GD, Principal Component Analysis and its interpretations			nterpretations,	
Singular Value Dec	omposition, Auto encoders and relation to PCA, Regularization in auto encoders, De-noising	auto encoders	s, Sparse auto	

UNIT-III Regularization 8 hours

Regularization: Bias Variance Trade-off, L1 and L2 regularization, Drop-outs, Early stopping, Dataset augmentation, Greedy Layer-wise Pretraining, Soft-max layer, Weight initialization methods, Batch Normalization, Learning Vectorial Representations of Words.

UNIT-IV Convolutional Neural Networks 8 hours

Convolutional Neural Networks: Convolution, Padding, Stride, Pooling, LeNet, AlexNet, ZF-Net, VGGNet, ResNet, DenseNet.

UNIT-V Recurrent Neural Networks

Recurrent Neural Networks, Back propagation through time (BPTT), Vanishing and Exploding Gradients, Truncated BPTT, GRU, LSTMs, Encoder Decoder Models.

8 hours

Course Outcomes: At the end of this course students will demonstrate the ability to

encoders.

CO 1	Describe the fundamental concepts, history, and architecture of neural networks and deep learning.	K2
CO 2	Implement and analyze gradient-based optimization algorithms and dimensionality reduction techniques like	K4
	PCA.	
CO 3	Apply regularization methods and optimization strategies to train efficient deep learning models.	K5
CO 4	Compare and contrast popular deep learning architectures such as CNNs (LeNet, AlexNet, VGG, ResNet,	K4
	etc.).	
CO 5	Design and implement RNN, LSTM, and GRU-based models for sequential data analysis.	K3
Text books:		
1. Iai	n Goodfellow and Yoshua Bengio and Aaron Courville, Deep learning, MIT Press, 2016	
Reference Boo	oks:	
1. Ni	elsen, Michael A. Neural Networks and Deep Learning. Determination Press, 2015.	
2. Ma	achine Intelligence: Demystifying Machine Learning, Neural Networks and Deep Learning, Notion Press, 2019.	
3. Kı	ımar Satish, "Neural Networks", Tata Mc Graw Hill.	
NPTEL/ You'	Гube/ Faculty Video Link:	
Unit I	https://www.youtube.com/watch?v=OBFZPivcdqg	
Unit II	https://www.youtube.com/watch?v=4TC5s_xNKSs	
Unit III	https://www.youtube.com/watch?v=xbYgKoG4x2g	
Unit IV	https://www.youtube.com/watch?v=aPfkYu_qiF4	
Unit V	https://www.youtube.com/watch?v=wPz3MPl5jvY	

	Bachelor of Technology Third Year		
<b>Course Code</b>	BEC0613 L	T P	Credits
Course Title	VLSI Testing and Reliability 3	0 0	3
<b>Course Objective</b>	es: The student will learn about		•
1	Basics of testing and fault modelling		
2	Testing and testability of combinational circuits		
3	Testing and testability of combinational circuits		
4	Built-in Self-Test (BIST), Memory and delay faults including IDDQ Testing		
5	Verification using UVM		
<b>Pre-requisites:</b> F	undamental knowledge of VLSI circuits		
	Course Contents / Syllabus		
UNIT-I	Introduction to VLSI Testing		8 hours
Introduction, Prin	ciple of testing, Types of testing, DC and AC parametric tests, Fault modelling, Stuck-at fault, Fault equivalent	nce, Fa	ult collapsing,
Fault dominance,	Fault simulation, Temporary Faults, Testing of Chips, Automatic test equipment.		
UNIT-II	Test Generation Basics		8 hours
Test generation ba	asics, Test generation algorithms, Path sensitization, Boolean difference, D-algorithm, Testable combination	al logic	circuit design,
The Reed Mullar	Expansion Technique, Three-Level OR AND-OR Design, Automatic Synthesis of Testing Logic, Testable	Design	n of Multilevel
Combinational C	ircuits, Synthesis of Random Pattern Testable Combinational Circuits, Path Delay Fault Testable Combin	ational	Logic Design,
Testable PLA Des	<del>U</del>		
UNIT-III	Testing of Sequential Circuits		8 hours
C 1	tial circuits as iterative combinational circuits, state table verification, test generation based on circuit structu		
*	s, Ad Hoc design rules, scan path technique (scan design), Partial scan, Level Sensitive Scan Design, R	andom	Access Scan
	l Scan, Testable Sequential Circuit Design Using Non scan Techniques, Cross Check, Boundary Scan.		<del>,</del>
UNIT-IV	Test Pattern Generation		8 hours
	ration of Built-in Self-Test (BIST), Output Response Analysis, Circular BIST, BIST Architectures. Testable		
	algorithms for RAMs, Delay faults, Delay test, IDDQ testing, testing methods, limitations of IDDQ Testing,	BIST	Techniques for
	Generation and BIST for Embedded RAMs.		T
UNIT-V	Introduction to Universal Verification Methodology		8 hours
	Universal Verification Methodology (UVM), Transaction, Test bench & its component, UVM class factor	•	
1 0,	Under Test (DUT) and its connection with environment, Scoreboards, coverage, predictors, monitors, Hierard	-	,
	ices in UVM, Configuration, Introduction of sequences, Multiple Sequences configuration, UVM register Marketine in UVM, Configuration, UVM, Co	Aodel,	RM & its use
in verification, RI	M integration, TLM (Transaction Level Modelling).		

CO 1	Understand the basics of testing and fault modelling	K1,K2
CO 2	Analyze the testing and testability of combinational circuits	K2
CO 3	Understand and analyze the testing and testability of combinational circuits	K4,K6
CO 4	Understand the Built-in Self-Test (BIST) and Memory and delay faults including IDDQ Testing	K4 ,K5
CO 5	Understand the Verification using UVM	K1,K3
Text books:		1
1. N.	K. Jha and S. G. Gupta, "Testing of Digital Systems", Cambridge University Press.	
2. M	L. Bushnell and V. D. Agrawal, "Essentials of Electronic Testing for Digital, Memory and Mixed Signal VLSI Circ	cuits", Kluwar
Ac	rademic Publishers	
3. P.	K. Lala, "Digital Circuit Testing and Testability", Academic Press	
Reference Bo	oks:	
1. Za	inalabe Navabi, "Digital System Test and Testable Design: Using HDL Models and Architectures", Springer	
2. M	Abramovici, M.A. Breuer and A.D. Friedman, "Digital Systems and Testable Design", Jaico Publishing House.	
NPTEL/ You'	Гube/ Faculty Video Link:	
Unit I	https://www.youtube.com/watch?v=ynKZLc-wtQA	
Unit II	https://www.youtube.com/watch?v=MgCFUO2BrkQ	
Unit III	https://www.youtube.com/watch?v=X7oB78Rq-0s	
Unit IV	https://www.youtube.com/watch?v=t4h1Jb5aQxM	
Unit V	https://www.youtube.com/watch?v=xAhbTylDT6k	

	Bachelor of Technology Third Year		
<b>Course Code</b>	BEC0616	LTP	Credits
<b>Course Title</b>	Real Time Operating System	300	3
<b>Course Objectiv</b>	ves: The student will learn about		
1	Embedded OS internals.		K2
2	The basic concepts of Real Time Operating System.		K2
3	Concepts of Process and Task Scheduling.		K3
4	Strategies to interface memory and I/O with RTOS kernel.		K4
5	Architecture of CMSIS-RTOS & process of RTX task management.		K3
Pre-requisites: 1	Basic fundamental of microprocessor, microcontroller & Embedded System		
	Course Contents / Syllabus		
UNIT-I	Linux Internals		8 hours
Linux internals:	Process Management, File Management, Memory Management, I/O Management. Overview of PC	SIX APIs, Thre	eads - Creation
Cancellation, PC	OSIX Threads Inter Process Communication – Semaphore, Pipes, FIFO, Shared Memory Kern	nel: Structure,	Kernel Modul
Programming Sc	hedulers and types of scheduling. Interfacing: Serial, Parallel Interrupt Handling Linux Device Dri	vers: Character,	USB, Block &
Network.		,	ŕ
UNIT-II	OS Overview		8 hours
OS overview: C	OS components, OS structure, Types of Operating Systems, Basics of RTOS: Real-time conce	epts, Characteris	stics of RTOS
Architecture of F	RTOS, Classification of RTOS: Hard Real time and Soft Real-time, Firm real time system, Advanta	ige and disadvar	ntage of RTOS
UNIT-III	Process		8 hours
Process: Introduct	tion, Memory lay out of an executing program, Process control block, Process creation, Process T	ermination, Con	ntext Switchin
and States.			
UNIT-IV	Concurrency		8 hours
Concurrency: Co	oncurrency Scheduling, Multiprocessing environment, Read-write by multiple CPUs and consis	tency problem,	Solutions wit
	on, Hardware Mutex, Software Mutex, Example: Dekker's algorithm, Semaphore, Deadlock,		
	rocesses Need Memory, Address Binding & its types, Memory Hierarchy, Virtual Memory,		
	th Paging, File System, File Structure, Directory Structure, Disk, Interrupt & DMA.	J	<i>U, U</i>
UNIT-V	Introduction to RTX		8 hours
RTX : RTX stru	cture, RTX files, RTX task and time management, Simple Time Management APIs, Task Priorit	y Scheme in R7	ΓX, Inter-Task
	Event, Interrupt, Mutex, Semaphore, Mailboxes and Messages in RTX, RTX control functions, A	•	
Course Outcom	age At the end of this source students will demonstrate the ability to	-	
Course Outcom	es: At the end of this course students will demonstrate the ability to		

СО	Explain the basics Embedded OS internals.	K1, K2
CO	Realize the basic concepts of RTOS.	K1, K4
CO	Apply the concepts of Process and Task Scheduling.	К3
CO	Implement strategies to interface memory and I/O with RTOS kernel.	K2
CO	Analyze the architecture of CMSIS-RTOS & process of RTX task management.	K2, K4
Text books		1
1. Jo	onathan W. Valvano, "Real-Time Operating Systems for ARM Cortex-M Microcontrollers" Jonathan Valvano; 4 edition	l.
2. Je	erry Cooperstein, "Writing Linux Device Drivers: A Guide with Exercises", J. Cooperstein publishers, 2009	
Reference Bo	ooks	
1. Q	ing Li and CarolynYao,"Real Time Concepts for Embedded Systems" - Qing Li, Elsevier ISBN:1578201241 CMP B	ooks © 2000
NPTEL/ You	Tube/ Faculty Video Link:	
Unit I	https://youtu.be/T0bgf3V7u-E	
Unit II	https://youtu.be/bJjgyTQ-BT4	
	https://youtu.be/M7JxDHUW5cc	
	https://youtu.be/JfrcMYBouJE	
Unit III	https://youtu.be/MrNafUqh860	
	https://youtu.be/gLTlQPYY_pw	
Unit IV	https://youtu.be/j3_Ck5oP5oI	
	https://youtu.be/q1J0VAYFkHg	
Unit V	https://youtu.be/kSzramCsHA4	
	https://youtu.be/nlwH07G9Efg	

Bachelor of Technology Third Year		
Course Code BEC0651	LTP	Credits
ourse Title IoT Architecture and Protocols	006	3
ourse Objectives: The student will learn about		
To understand the components, layers, and architecture of IoT systems including device, network, and a layers.	pplication	K2
To develop the ability to interface sensors with microcontrollers and transmit sensor data to the classification platforms like ThingSpeak and Blynk.	oud using	K2
To explore various communication protocols and standards in IoT such as UART, Bluetooth, LoRaW IoT, and M2M.	/AN, NB-	K1
To evaluate the differences and capabilities of IoT architectures and middleware platforms including OIC and WoT.	, IoTivity,	K2
To simulate and design data communication and control in IoT systems using dashboards, cloud integral lightweight data formats	ration, and	K3
e-requisites: Basic of IoT devices		
Course Contents / Syllabus		
NIT-I Reference Architecture		8 hours
oT-An Architectural Overview—Building an architecture, Main design principles and needed capabilities, IoT Reference unctional View, Information View, Deployment and Operational View, Other Relevant architectural views. Realtroduction, Technical Design constraints, Data representation and visualization, Interaction and remote control, Windows	l-World Desig	gn Constraint
NIT-II IoT Architecture		8 hours
Γ Open-source architecture (OIC)- OIC Architecture & Design principles- IoT Devices and deployment models- I ck - Overview- IoTivity stack architecture- Resource model and Abstraction. LoRaWAN architecture, Channel acce Γ.		
NIT-III IoT Connectivity Protocols		8 hours
Γ Connectivity Overview, Wireless Long Range (WAN) Protocols, LAN Protocols, Serial Protocols, IoT transmitotocols, Features and security in Bluetooth.	ssion Protoco	ls, Wired LA
NIT-IV IoT Layered Protocols		8 hours
otocol Standardization for IoT, Efforts, M2M and WSN Protocols, SCADA and RFID Protocols, Issues with IoT Standards Protocols IEEE802.15.4, IEEE 802.11, BAC Net Protocol Modbus, KNX, architecture and Protocol stack uses layer.		
NIT-V Web of Things		8 hours
Veb of Things versus Internet of Things, Two Pillars of the Web, Architecture Standardization for WoT, Platform M Iultitier WoT Architecture, WoT Portals and Business Intelligence.	iddleware for	WoT, Unified
ourse Outcomes: At the end of this course students will demonstrate the ability to	_	

CO 1	Understand the layered architecture and functional components of IoT systems and apply them to real-world applications	K2
CO 2	Implement cloud-based data transmission and remote-control using platforms such as ThingSpeak, Blynk, and IoT dashboards.	К3
CO 3	Analyze communication protocols and technologies including LoRa, NB-IoT, Bluetooth, and serial communication for IoT systems.	K4
CO 4	Evaluate and compare open-source IoT architectures (OIC, IoTivity, WoT) based on scalability, interoperability, and middleware capabilities.	K5
CO 5	Design and simulate M2M, WSN, and cloud-integrated systems using ESP32, LoRa modules, and JSON data representation.	K5

#### **Text Books:**

- 1. Vijay Madisetti and ArshdeepBahga, "Internet of Things (A Hands-on-Approach)",1st Edition, VPT, 2014.
- 2. Francis daCosta, "Rethinking the Internet of Things: A Scalable Approach to Connecting Everything", 1st Edition, Apress Publications, 2013.
- 3. Cuno P fister, Getting Started with the Internet of Things, O" Reilly Media, 2011, ISBN: 978-1.

# **Reference Books:**

- 1. Honbo Zhou, "The Internet of Things in the Cloud: A Middleware Perspective", CRC Press, 2012.
- 2. Dieter Uckelmann, Mark Harrison, Michahelles, Florian (Eds), "Architecting the Internet of Things", Springer, 2011.
- 3. David Easley and Jon Kleinberg, "Networks, Crowds, and Markets: Reasoning About a Highly Connected World", Cambridge University Press, 2010.

## Links: NPTEL/You Tube/Web Link

Unit I	https://onlinecourses.nptel.ac.in/noc21_cs20/unit?unit=49&lesson=53
Unit II	https://www.youtube.com/watch?v=FRxRT0DjE7A
<b>Unit III</b>	https://onlinecourses.nptel.ac.in/noc19_cs65/unit?unit=15&lesson=20
<b>Unit IV</b>	https://onlinecourses.nptel.ac.in/noc19_cs65/unit?unit=15&lesson=19
Unit V	https://www.youtube.com/watch?v=R52OCMtFqNA

#### **List of Practical:**

S.No	Name of Experiment	CO Mapping
1	Understand the layers and components of a basic IoT system.	CO1
2	Transmitting Sensor Data to Cloud (Thing Speak). Send live data from a sensor to a cloud server.	CO1
3	Building a Simple IoT Dashboard to understand data visualization in IoT.	CO1

4	Remote Device Control using Blynk App to enable remote control in an IoT system.	CO1
5	Create JSON strings from sensor data to Explore data formats used in IoT communication.	CO1
6	Analyze a real-life IoT application using reference architecture views. Select a use case (e.g., smart parking).	CO1
7	Understand and compare Open Interconnect Consortium (OIC) and other IoT architectures to Explore OIC and one other architecture (e.g., oneM2M, AllJoyn).	CO1
8	Install and configure IoTivity stack for experimentation.	CO2
9	Explore and analyze the LoRaWAN architecture.	CO2
10	Simulation of LoRaWAN Communication Using LoRa Module to Transmit data between two LoRa devices.	CO2
11	Study channel access and scheduling in NB-IoT to Simulate narrowband communication using NS3 or theoretical Modeling.	CO2
12	Understand serial protocol (UART) communication in IoT. Interface ESP32 with PC via UART.	CO3
13	Interface and control IoT devices using Bluetooth.	CO3
14	Simulate communication between machine-to-machine (M2M) and wireless sensor network (WSN) nodes.( Use two ESP32 boards to simulate sensor-to-sensor data transmission over Wi-Fi.)	CO4
15	Understand conceptual and architectural differences between Web of Things and Internet of Things.	CO5

	Bachelor of Technology Third Year		
Course Code	<u>.</u>	T P	Credits
Course Title	Digital Signal Processing 0	06	3
<b>Course Objectives:</b> T	The student will learn about		
1. Basics of MAT	LAB signal processing toolbox, Scilab, code composer studio and basic signal operation.		
2. Analysis of DF	T and fast Fourier transform spectrum from numerical data.		
3. Examine the co	ncept of digital IIR filter design.		
4. Analysis the co	ncept of digital FIR filter design.		
5. Analysis of mu	lti-rate signal processing & adaptive signal processing.		
Pre-requisites: Basic 1	knowledge of Digital system design and Computer System.		
	Course Contents / Syllabus		
UNIT-I	Basics of signal Processing, DFT & FFT		8 hours
Basics of signal proce	essing, classification of signal processing, Applications of Digital Signal Processing in the real world. F	requer	ncy Analysis
Discrete-Time System	ns: Discrete Time Fourier Transform (DTFT), Discrete Fourier Transform (DFT), Properties of the DFT	, Relati	ionship of DF
with DTFT & Z- trans	form. Linear Filtering using Circular Convolution and Linear Convolution. Fast Fourier Transform: Rad	ix-2 D	IT-FFT & DII
	e DFT using FFT algorithm.		
L.	Design of IIR Digital Filters		8 hours
Introduction to Filters,	Classification of filter, Characteristic of digital filters, Filter Design Specifications. Filter Transformatio	n Toch	
Invariant Transformation	on, Bi-Linear Transformation, All-Pole Analog Filters: Butterworth and Chebyshev, Analog frequency to		
Invariant Transformation of Digital Butterworth,	on, Bi-Linear Transformation, All-Pole Analog Filters: Butterworth and Chebyshev, Analog frequency to and Chebyshev Filters, digital frequency transformation.		mation, Desig
Invariant Transformation of Digital Butterworth, UNIT-III	on, Bi-Linear Transformation, All- Pole Analog Filters: Butterworth and Chebyshev, Analog frequency to and Chebyshev Filters, digital frequency transformation. <b>Design of FIR Digital Filter</b>	ransfor	mation, Desig
Invariant Transformation of Digital Butterworth, UNIT-III	on, Bi-Linear Transformation, All-Pole Analog Filters: Butterworth and Chebyshev, Analog frequency to and Chebyshev Filters, digital frequency transformation.	ransfor	mation, Desig
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CO 2	Design the digital IIR filters using various transformation techniques.	K4
CO 3	Design and analyse the FIR Filters and the effect of finite word length in digital filter.	K4
CO 4	Realize the digital system through different methods of realization structures and their utilities	K3
CO 5	Explain the concept of multirate and adaptive signal processing.	K2

#### **Text Books:**

- 1. John G Prokias, Dimitris G Manolakis, "Digital signal processing Principles Algorithms & Applications", 4th edition, Pearson education, 2007.
- 2. Oppenheim & Schafer, "Discrete Time Signal Processing", Pearson education, Prentice Hall, 2nd edition, 2003.

#### **Reference Books:**

- 1. Johnny R. Johnson, "Digital Signal Processing", 3rd edition, PHI Learning pvt ltd., 2009 Reference Books.
- 2. S.Salivahanan, "Digital signal processing", 6th edition, McGraw Hill Education pvt ltd.
- 3. Tarun K. Rawat, "Digital Signal Processing",1st edition, Oxford University Press, 2015. 3. S.K. Mitra, 'Digital Signal Processing—A Computer Based Approach, McGraw Hill, 4th Edition.

## Links: NPTEL/You Tube/Web Link

Unit I	https://youtu.be/Q8wuqYsdnSs
Unit II	https://youtu.be/3QWvi8EC_DI
Unit III	https://youtu.be/Xl5bJgOkCGU
Unit IV	https://youtu.be/Z1N0qeiw9oE
Unit V	https://youtu.be/HVGW85eGPQQ

#### List of Practical:

S.No	Name of Experiment	CO
5.110	Name of Experiment	Mapping
1	Introduction to MATLAB/ Scilab and Code Composer Studio or its equivalent open-source software.	CO1
2	To study matrix multiplication using code composer studio.	CO1
3	Write a MATLAB program to perform the various matrix operations: addition, subtraction, multiplication, and inverse of the given sequences.	CO1
4	To generate the different type of signals such as unit impulse, unit step, ramp, exponential, sinusoidal and cosine for both continuous and discrete time signal using MATLAB.	CO1
5	Write a MATLAB program to perform amplitude scaling, time-scaling and time shifting on a given signal $x(n)=u(2n-3)$ .	CO1
6	To perform various operations on signals such as addition, multiplication, scaling, shifting and folding, computation of energy and average power using MATLAB program.	CO1
7	To write a MATLAB program to compute autocorrelation and cross correlation between signals.	CO1
8	To write a MATLAB program to find the impulse response $\&$ step response of the LTI system governed by the transfer function $H(s) = 1/S 4s + 3$ .	CO1
9	To Write a MATLAB program to draw Pole-Zero map in Z-Plane.	CO1

10	To write a MATLAB program to find the impulse response& step response of the LTI system governed by the transfer function.	CO1
11	To write a MATLAB Program to generate of continuous time signals like unit step & sawtooth signal.	CO1
12	Write a MATLAB program to compute the autocorrelation of the sequence $x(n) = \{1,4,1,3\}$ .	CO1
13	Write a MATLAB program to plot a continuous time signal $x(t) = \cos(6\pi t)$ and its sampled version $x(nTs)$ , given that $ts=10$ Hz.	CO1
14	Write a MATLAB program to generate and plot a signal $x(n)=u(n)-u(n-10)$ . Also compute and plot the even and odd parts of $x(n)$ .	CO1
15	Determine the DTFT of $x(n)=(0.5)^n$ u(n). plots its magnitude, phase, real and complex part.	CO2
16	Evaluate the DFT and IDFT of a given sequences $x(n) = \{0,1,2,3\}$ and draw the magnitude and phase response of the output sequence using MATLAB.	CO2
17	Study of Discrete Fourier Transform (DFT) and its inverse using virtual Lab.	CO2
18	Analysis of DIT-FFT algorithm for a given sequence $x(n) = \{n+1\}$ for $n = 0, 1, 2, 3$ and draw the frequency spectrum of given signals.	CO2
19	Evaluate and verify the linear convolution of the given sequences $x(n) = \{0,1,0,1\}$ & $h(n) = \{2,3,4\}$ using MATLAB for linear filtering applications.	CO2
20	Evaluate and verify the circular convolution of the given sequences $x(n) = \{1,1,1,1\}$ & $h(n) = \{0,1,0,1\}$ using MATLAB for linear filtering applications.	CO2
21	To obtain linear convolution of the given sequences using code composer studio.	CO2
22	To obtain circular convolution of the given sequences using code composer studio.	CO2
23	To obtain DFT and IDFT of the given sequences using code composer studio.	CO2
24	To Implement Fast Fourier transform (FFT) to analyse the frequency spectrum of digital signals. Also evaluate the relative computational efficiency of the fast Fourier transform algorithm by using DMA based I/P and frame-based processing.	CO2
25	Verify Linear convolution of two sequences using FFT.	CO2
26	Verify Circular Convolution of two sequences using FFT.	CO2
27	To verify FFT as sample interpolator.	CO2
28	Design and analysis of a 2nd order analog Low Pass Butterworth IIR filter for a cut off frequency of 4 KHz also draw the pole-zero diagram, magnitude and phase response using FDA tool.	CO3
29	Design and analysis of a digital Low Pass and High Pass FIR filter using various rectangular and hamming windows for M=7.	CO3
30	IIR filter design using bilinear transformation method on scilab.	CO3
31	Filter Design and Analysis of HPF Butterworth Filter using FDA tool.	CO3
33	Filter Design and Analysis of BPF Butterworth Filter using FDA tool.	CO3

34	Filter Design and Analysis of BSF Butterworth Filter using FDA tool.	CO3
35	Study of Infinite Impulse Response (IIR) filter using virtual Lab.	CO3
36	Write a MATLAB program to design an FIR filter to meet the following specifications: pass band edge= 2 KHz, stopband edge= 5 KHz, passband attenuation=2 dB, stopband attenuation= 42 dB and sampling frequency= 20 KHz.	CO4
37	Write a MATLAB program to design am LPF with passband gain of unity, cut off frequency of 100 Hz and working sampling frequency of 5 KHz using rectangular window. Take the length of the impulse responses M=7.	CO4
38	Write a MATLAB program to design a digital low pass Butterworth filter to satisfy the following: As=16 dB, Ap=7dB $\Omega$ p=0.2 $\pi$ , $\Omega$ s=0.3 $\pi$ . Use the bilinear transformation method. Assume T=1 sec.	CO4
39	Write a MATLAB program for the zero-input limit cycle operation. Assume the input $x(n)=0.375 \delta$ , impulse response of the system $h(n)=(0.375)^n$ $u(n)$ , $(B+1)$ and rounding is used for quantization.	CO4
40	Write a MATLAB program to find $Q x $ by applying truncation in signed magnitude. Representation for a number $x=3/8$ . Assume a $(B+1)=3$ -bit register (including sign bit).	CO4
41	Design a digital resonator with a peak gain of unity at f=50 Hz and a 3dB bandwidth of 6 Hz, assuming a sampling frequency of 300 Hz. Plot its pole-zero diagram and magnitude response.	CO4
42	Study of FIR filter design using window method: Lowpass and high pass filter using virtual Lab.	CO4
43	Study of FIR filter design using window method: Bandpass and Band stop filter using virtual Lab.	CO4
44	To design FIR filter using various window function. Also explore the several different methods of measuring its characteristics in the time and frequency domains.	CO4
45	Design and analysis of decimation and interpolation of a given sequence $x(n) = \{1, 2, 2, 3, 2, 1\}$ for decimation factor D=4 and interpolation factor I=3.	CO5
46	Write a MATLAB program to observe the effect of down sampling in frequency domain.	CO5
47	Write a MATLAB program to observe the effect of up sampling in frequency domain.	CO5
48	To implement Tone Generation.	CO5
49	To implement floating point arithmetic.	CO5
50	To study about DSP Processors and architecture of TMS320C6713 DSP processor.	CO5
51	Generate a noisy signal, design a low-pass filter, apply the filter, and compare the power spectral density before and after filtering.	CO5
52	Design an adaptive filter that can adjust its coefficients to minimize noise or interference in a signal. Implement adaptive filtering algorithms like recursive least squares (RLS) to enhance signals in various applications.	CO5
53	To study and analysis of LMS algorithm for adaptive FIR filters. Also demonstrate Real-time implementations of noise cancellation and system identification.	CO5

Bachelor of Technology Third Year					
<b>Course Code</b>	BEC0614P LTP	Credits			
Course Title	Robotics Lab 0 0 2	1			
<b>Course Objectiv</b>	es: The student will learn about	•			
1	The basic features of KUKA sim pro software.				
2	The various programs on KUKA Sim Pro software.				
3	Basics of the KUKA KR10 robotics arm.				
4	Programming & Simulation of different task on KUKA KR10 robotics arm.				
<b>Pre-requisites:</b> N	Mechanics, kinematics, dynamics, basic electrical circuits				
	List of Experiments				
S.No	Name of Experiment	CO			
1	Study of KUKA sim pro/ABB Robot Studio software and its features.	CO1			
2	Create target, Create path, Create workobject move along the path-linear movement in KUKA sim pro/ABE Robot Studio software.	CO 1			
	Write a simulation program for welding task by using KUKA sim pro/ABB Robot Studio software.	CO 2			
3	Geometrical path generation				
	Automated circular path creation				
4	To write a simulation program for pick & place task on using KUKA sim pro/ABB Robot Studio software.	CO 2			
5	Study Teach pandent of KUKA /ABB Robotics Arm.	CO2			
6	Study Rapid Programming/ KRL programming and Write a program of pick and place using programming.	CO 3			
7	Simulation of finger gripper in KUKA sim pro with the help of a "move tower" project	CO 3			
8	To study about robotics arm KR 10 and its features.	CO 4			
9	To verify the simulation program for task of pick & place on robotic arm KR-10.	CO 4			
10	To verify the simulation program for welding task on robotic arm KR-10	CO 4			
Course Outcome	e: After successful completion of this Lab students will be able to	Blooms			
		Level			
CO 1	Understand the basic features of KUKA sim pro software/Robot Studio ABB Software.	K2			
CO 2	Understand and simulate the various programs on KUKA sim pro software/Robot Studio ABB Software.	K1, K5			
CO 3	Learn about the KUKA KR10 robotics arm.	K1, K2			
CO 4	Simulate various programs on KUKA KR10 robotics arm.	K5			

Bachelor of Technology Third Year					
<b>Course Code</b>	BEC0612P LTP	Credits			
Course Title	Image Processing and Pattern Recognition Lab 0 0 2	1			
<b>Course Objective</b>	es: The student will learn about				
1	Basic skills for image sharpening and image enhancement.				
2	Basic concept of image restoration and compression techniques.				
3	Basic concept of image segmentation for image analysis.				
4	Analyze the spatial/ texture feature of image.				
5	The use of various enhancement and segmentation techniques for developing computer vision application.				
Pre-requisites: B	asics of Python / MATLAB, Sampling, convolution, Fourier transform, frequency domain concepts				
	List of Experiments				
S.No	Name of Experiment	CO			
1	Write a program using MATLAB/Python to display grey scale/colour images.	CO 1			
2	Write a program using MATLAB/Python to extract different attributes (i.e., Geometrical and texture) of an Image.	CO 2			
3	Write a program using MATLAB/Python for Image Negation.	CO 2			
4	Write a program using MATLAB/Python for Power Law Transformation.	CO 2			
5	Write a program using MATLAB/Python for Histogram Mapping and Equalization.	CO 2			
6	Write a program using MATLAB/Python for Image Smoothening and Sharpening.	CO 1			
7	Write a program using MATLAB/Python for Edge Detection using Sobel, Prewitt and Roberts Operators.	CO 1			
8	Write a program using MATLAB/Python for Morphological Operations on Binary Images.	CO 3			
9	Write a program using MATLAB/Python for Pseudo Coloring.	CO 5			
10	Write a program using MATLAB/Python for the segmentation using watershed transform.	CO 3			
11	Write a program to eliminate the high frequency components of an image.	CO 5			
12	Write a program using MATLAB/Python to extract the image features for image segmentation using DWT Computation.	CO 4			
	: After successful completion of this Lab students will be able to	Blooms Level			
CO 1	Implement image sharpening and image enhancement algorithm.	K3, K4			
CO 2	Analyze the power of various image restoration and compression techniques.	K2, K3			
CO 3	Learn basic skills for image segmentation and image analysis.	K1, K2			
CO 4	Analyze the spatial/ texture features of image.	K2, K3, K4			
CO 5	Implement and evaluate different enhancement and segmentation techniques for developing computer vision applications.	K3, K4			

Bachelor of Technology Third Year					
Course Code	BEC0616P LTP	Credits			
Course Title	Real Time Operating System Lab 0 0 2	1			
	es: The student will learn				
About					
1	Understand the architecture and principles of RTOS.				
2	Learn task management, scheduling, synchronization, and inter-task communication using an RTOS.				
3	Implement real-time applications using an RTOS like CMSIS-RTOS, Free RTOS, or RTX.				
4	Perform hands-on experimentation on real or simulated embedded hardware (e.g., STM32, ARM Cortex-M).				
Pre-requisites: M	licrocontroller architecture, GPIO, timers, serial communication protocols				
	List of Experiments				
S.No	Name of Experiment	CO			
1	Setup of toolchain (e.g., Keil uVision, STM32CubeIDE), Introduction to CMSIS-RTOS or FreeRTOS. Blinking LED without RTOS vs. with RTOS.	CO1			
2	Create multiple tasks with different priorities; demonstrate task switching and preemption.	CO1			
3	Use osDelay, vTaskDelay, and timers. Measure task execution time.	CO2			
4	Change task priorities dynamically and observe scheduling behavior.	CO2			
5	Use binary and counting semaphores for task synchronization	CO3			
6	Implement inter-task communication using message queues.	CO3			
7	Use mailboxes or event flags for signaling between tasks.	CO4			
8	Use software timers for delayed and periodic task execution.	CO4			
9	Explore static and dynamic memory allocation APIs in RTOS.	CO4			
10	Implement Round Robin, Rate Monotonic (RM), or Earliest Deadline First (EDF) scheduling.	CO4			
Course Outcome	: After successful completion of this Lab students will be able to	Blooms Level			
CO 1	Apply the concepts of RTOS architecture and kernel components in real-time embedded systems.	К3			
CO 2	Implement task management, scheduling, synchronization, and inter-task communication using RTOS APIs.	K4			
CO 3	Develop and test multitasking applications using CMSIS-RTOS, FreeRTOS, or RTX on ARM Cortex-M	K5			
CO 4	Analyze the responsiveness of real-time applications through practical experiments on embedded simulators	K4			

~ ~ •	Bachelor of Technology Third Year	T (D) D	O 11.
Course Code		LTP	Credits
Course Title		200	NC
Course Objective	es: The student will learn about		
1	Learn the legacies of constitutional development in India and understand the most diversified legal do	cument	K1, K2
	of India and philosophy behind it.		
2	Aware of the theoretical and functional aspects of the Indian Parliamentary System.		K1
3	Understand the legal concepts and its implications for engineers.		K2
4	Learn the law of intellectual property rights.		K1
5	Learn the role of engineering in business organizations and e-governance.		K1
Pre-requisites: P	olitical science		
	Course Contents / Syllabus		
UNIT-I	Introduction and Basic Information about Indian Constitution		6 hours
Meaning of the co	nstitution law and constitutionalism, Historical Background of the Constituent Assembly, Government of	f India Ac	t of 1935 a
Indian Independer	ace Act of 1947, Enforcement of the Constitution, Indian Constitution and its Salient Features, The Pream	nble of the	Constitutio
Fundamental Righ	nts, Fundamental Duties, Directive Principles of State Policy, Parliamentary System, Federal System, C	Centre- Sta	ate Relation
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Amendment of the	e Constitutional Powers and Procedure, The historical perspectives of the constitutional amendment	ts in India	
	ne Constitutional Powers and Procedure, The historical perspectives of the constitutional amendment and Emergency, President Rule, Financial Emergency, and Local Self Government – Constitutional Scheme		, Emergeno
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Sole Traders, Partnerships: Companies: The Company's Act: Introduction, Formation of a Company, Memorandum of Association, Articles of Association, Prospectus, Shares, Directors, General Meetings and Proceedings, Auditor, Winding up.

E-Governance and role of engineers in E-Governance, Need for reformed engineering serving at the Union and State level, Role of I.T. professionals in Judiciary, Problem of Alienation and Secessionism in few states creating hurdles in Industrial development.

	Course Outcomes	: At	the	end of	this	cours	e stu	dents	will	dem	onst	rate	e the	e abi	lity to	0
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CO 1	Identify and explore the basic features and modalities about Indian constitution.						
CO 2	Differentiate and relate the functioning of Indian parliamentary system at the center and state level.	K2, K3					
CO 3	Differentiate different aspects of Indian Legal System and its related bodies.	K2					
CO 4	Discover and apply different laws and regulations related to engineering practices.	К3					
CO 5	Correlate role of engineers with different organizations and governance models	K4					

#### Text books:

- 4. M Laxmikanth: Indian Polity for civil services and other State Examination,6th Edition, Mc Graw Hill.
- 5. Brij Kishore Sharma: Introduction to the Indian Constitution, 8th Edition, PHI Learning Pvt. Ltd.
- 6. Prabudh Ganguli: Gearing up for Patents: The Indian Scenario, Orient Longman.

## **Reference Books:**

- 4. BL Wadehra: Patents, Trademarks, Designs and Geological Indication Universal Law Publishing LexisNexis.
- 5. Executive programme study material Company Law, Module II, by ICSI (The Institute of Companies Secretaries of India) (Only relevant sections i.e., Study 1, 4 and https://www.icsi.edu/media/webmodules/publications/Company%20Law.pdf
- 6. Handbook on e-Governance Project Lifecycle, Department of Electronics & Information Technology, Government of India, https://www.meity.gov.in/writereaddata/files/eGovernance\_Project\_Lifecycle\_Participant\_Handbook-5Day\_CourseV1\_20412.pdf

## Links:

Unit 1	https://legalaffairs.nalsar.ac.in/students/student/course-details/1
Unit 2	https://www.youtube.com/watch?v=lZ2tvimrLRQ&t=281s
Unit 3	https://www.youtube.com/watch?v=H0_olSSX6D8&t=2s
Unit 4	https://www.youtube.com/watch?v=WvduZOWoft0
Unit 5	https://www.youtube.com/watch?v=7SmrFh88Cuk

	Bachelor of Technology Third Year		
<b>Course Code</b>	BNC0602 L 7	P	Credits
<b>Course Title</b>	Essence of Indian Traditional Knowledge 2 0	0	NC
<b>Course Objectives</b>	s: The student will learn about		
	to provide basic knowledge about different theories of society, state and polity in India, Indian literature	, cultu	re, Indian
	y, science, management, cultural heritage and different arts in India.		
Pre-requisites: Ba	sic science and Indian Culture		
	Course Contents / Syllabus		
UNIT-I	Society State and Polity in India		6 hours
, Council of Minister in Ancient India, F	dia: Evolutionary Theory, Force Theory, Mystical Theory Contract Theory, Stages of State Formation in An ers Administration Political Ideals in Ancient India Conditions' of the Welfare of Societies, The Seven Limbs Purusārtha, Varnāshrama System, Āshrama or the Stages of Life, Marriage, Understanding Gender as a Women in Historical traditions, Challenges faced by Women.	of the	State, Society
UNIT-II	Indian Literature, Culture, Tradition and Practices		6 hours
	and languages in India: Harappan Script and Brahmi Script. The Vedas, the Upanishads, the Ramayana a		
Puranas, Buddhist Literature, Kannad Literature	And Jain Literature in Pali, Prakrit And Sanskrit, Sikh Literature, Kautilya's Arthashastra, Famous Sans la Literature, Malayalam Literature, Sangama Literature Northern Indian Languages & Literature, Persi	krit Au	nthors, Telugu l Urdu ,Hindi
Puranas, Buddhist Literature, Kannad Literature UNIT-III	And Jain Literature in Pali, Prakrit And Sanskrit, Sikh Literature, Kautilya's Arthashastra, Famous Sans la Literature, Malayalam Literature, Sangama Literature Northern Indian Languages & Literature, Persi Indian Religion, Philosophy and Practices	crit Au an Anc	thors, Telugud Urdu ,Hindi
Puranas, Buddhist Literature, Kannad Literature UNIT-III Pre-Vedic and Ved	And Jain Literature in Pali, Prakrit And Sanskrit, Sikh Literature, Kautilya's Arthashastra, Famous Sans la Literature, Malayalam Literature, Sangama Literature Northern Indian Languages & Literature, Persi Indian Religion, Philosophy and Practices dic Religion, Buddhism, Jainism, Six System Indian Philosophy, Shankaracharya, Various Philosophica	crit Au an And	thors, Telugud Urdu ,Hind
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Puranas, Buddhist Literature, Kannad Literature UNIT-III Pre-Vedic and Ved Heterodox Sects, B UNIT-IV	And Jain Literature in Pali, Prakrit And Sanskrit, Sikh Literature, Kautilya's Arthashastra, Famous Sans la Literature, Malayalam Literature, Sangama Literature Northern Indian Languages & Literature, Persi Indian Religion, Philosophy and Practices dic Religion, Buddhism, Jainism, Six System Indian Philosophy, Shankaracharya, Various Philosophica Shakti Movement, Sufi movement, Socio religious reform movement of 19th century, Modern religious practices, Management and Indian Knowledge System	crit Au nn And l Doct tices.	thors, Telugud Urdu ,Hind  4 hours  rines , Other  4 hours
Puranas, Buddhist Literature, Kannad Literature UNIT-III Pre-Vedic and Ved Heterodox Sects, B UNIT-IV Astronomy in Indi Geography, Biolog	And Jain Literature in Pali, Prakrit And Sanskrit, Sikh Literature, Kautilya's Arthashastra, Famous Sans la Literature, Malayalam Literature, Sangama Literature Northern Indian Languages & Literature, Persi Indian Religion, Philosophy and Practices dic Religion, Buddhism, Jainism, Six System Indian Philosophy, Shankaracharya, Various Philosophica Shakti Movement, Sufi movement, Socio religious reform movement of 19th century, Modern religious practices.  Science, Management and Indian Knowledge System  a, Chemistry in India, Mathematics in India, Physics in India, Agriculture in India, Medicine in India, ty, Harappan Technologies, Water Management in India, Textile Technology in India, Writing Technology	rit Au an And l Doct tices.	thors, Telugud Urdu ,Hind  4 hours  rines , Other  4 hours  urgy in India
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# **Text books:**

- 1. Sivaramakrishna (Ed.), Cultural Heritage of India-Course Material, Bharatiya Vidya Bhavan, Mumbai, 5th Edition, 2014.
- 2. S. Baliyan, Indian Art and Culture, Oxford University Press, India
- 3. Nitin Singhania, Indian Art and Culture: for civil services and other competitive Examinations,3rd Edition,Mc Graw Hill

# **Reference Books:**

- 1. Romila Thapar, Readings In Early Indian History Oxford University Press, India
- 2. Basham, A.L., The Wonder that was India (34th impression), New Delhi, Rupa & co.